

SDNL104 - transitory Under-structuring nonlinear: shock of a beam on 1 support

Summary:

The scope of application of this test relates to the dynamics of the structures, and more particularly the calculation of transitory answer nonlinear per dynamic under-structuring.

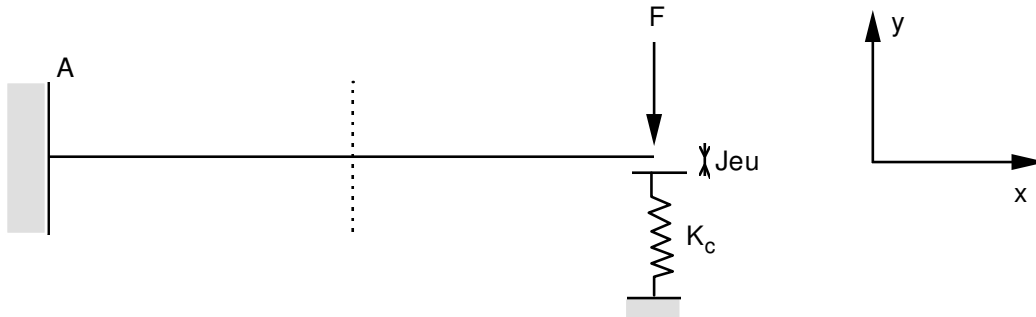
It is a question of calculating the nonlinear transitory answer of a beam in inflection with shock on a support elastic and subjected to a constant force as from the initial moment. The beam is modelled by elements of the type `POU_D_E` (model beam of Euler).

The results of reference result from a direct transitory calculation on the model not substructure, by using the operator `DYNA_NON_LINE`. This test thus makes it possible to validate the computational tools of response transitory by under - structuring, in the case of the taking into account of non-linearities of type shock on a fixed obstacle.

One also checks the interest of the static modes to enrich the base by projection and the orthogonalisation of the base.

1 Problem of reference

1.1 Geometry



The length of the beam is worth: $L = 1 \text{ m}$

The section of the beam is full circular of ray: $R = 0.1 \text{ m}$

The game between the beam and the elastic support is worth: $J = 1 \cdot 10^{-4} \text{ m}$

1.2 Material properties

$$E = 1.10^{10} \text{ Pa}$$

$$\nu = 0.3$$

$$\rho = 1.10^6 \text{ kg/m}^3$$

The stiffness within the competence of contact is worth: $K_c = 1.10^8 \text{ N/m}$

1.3 Boundary conditions and loadings

On all the structure: $DX = DZ = DRY = DRX = 0$.

At the point A : $DY = DRZ = 0$.

At the loose lead of the beam: as from the moment $t = 0 \text{ s}$, $F_y = -1000 \text{ N}$

1.4 Initial conditions

Structure initially at rest.

2 Reference solution

2.1 Method of calculating used for the reference solution

The reference solution is given by a direct transitory calculation using the operator `DYNA_NON_LINE` (modeling A).

2.2 Results of reference

Value displacements, speed of the loose lead of the beam according to the direction Y at the moment when their values are maximum, i.e. with $t=0.1315\text{ s}$ for displacement and with $t=0.1566\text{ s}$ for speed.

	Displacement (m)	Speed ($m.s^{-1}$)
Diagram of Newmark	-1.853E-06	-0.00463

2.3 Uncertainty on the solution

Digital solution.

3 Modeling A

3.1 Characteristics of modeling

The beam is with a grid in segments to which are affected of the elements of the type POU_D_E.

3.2 Characteristics of the grid

Many nodes: 11

Many meshes and types: 10 SEG2

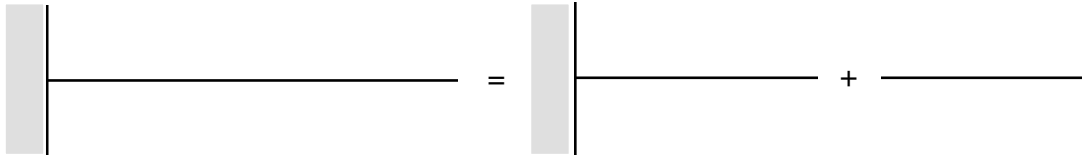
3.3 Actual values: references for modeling B

Identification	Aster
Diagram of Newmark	
Displacement (m)	-1.853E-06
Speed ($m.s^{-1}$)	-0.00463

4 Modeling B

4.1 Characteristics of modeling

The beam is cut out in 2 parts of equal size. Each substructure considered is with a grid in segments to which are affected of the elements of the type `POU_D_E`.



The structure is studied using the method of under-structuring with interfaces of the type “Craig - Bampton” (blocked interfaces).

The base of the first 5 clean modes of the complete structure is calculated by under - structuring. Then, the transitory problem, project on this basis, are solved by the transitory operator of calculation by modal recombination.

4.2 Characteristics of the grid

Many nodes: 6

Many meshes and types: 5 `SEG2`

4.3 Sizes tested and results

Identification	Reference	Aster	% difference
Diagram of integration of Euler			
Displacement (m)	-1.85356E-06	-1.71889E-06	7.265%
Speed ($m.s^{-1}$)	-4.63289E-3	-4.486745E-3	3.154%
Diagram of Devogelaere			
Displacement (m)	-1.85356E-06	-1.71881E-06	7.269%
Speed ($m.s^{-1}$)	-4.63289E-3	-4.486672E-3	3.156%
Diagram with step of adaptive time of order 2			
Displacement (m)	-1.85356E-06	-1.71880E-06	7.270%
Speed ($m.s^{-1}$)	-4.63289E-3	-4.486748E-3	3.154%

5 Modeling C

5.1 Characteristics of modeling

The beam is with a grid with elements of the type `POU_D_E`.

The transitory problem is solved in a direct way on various basic types of projection.

With the problem is dealt for four types of projection:

- on a basis made up of the first 5 normal modes;
- on a basis made up of the first 5 normal modes enriched by a static mode;
- on a basis made up of the first 5 normal modes enriched by a static mode and orthogonalisation by the base compared to the matrix by stiffness using the operand `ORTHO=' OUI '` of `DEFI_BASE_MODAL` ;
- on a basis made up of the first 5 normal modes enriched by a static mode and orthogonalisation by the base compared to the matrix by stiffness using the operand `ORTHO_BASE` of `DEFI_BASE_MODAL` .

5.2 Characteristics of the grid

Many nodes: 11

Many meshes and types: 10 `SEG2`

5.3 Actual values:

Identification	Reference	Aster	% difference
Base without static mode			
Displacement (<i>m</i>)	-1.85356E-06	-1.7223385E-06	7.07977%
Speed (<i>m.s</i> ⁻¹)	-4.63289E-03	-4.48406E-03	3.212%
Base with static mode			
Displacement (<i>m</i>)	-1.85356E-06	-1.88612E-06	1.7566%
Speed (<i>m.s</i> ⁻¹)	-4.63289E-03	-4.65969E-03	0.578%
Base with static mode + <code>ORTHO=' OUI '</code>			
Displacement (<i>m</i>)	-1.85356E-06	-1.88612E-06	1.7566%
Speed (<i>m.s</i> ⁻¹)	-4.63289E-03	-4.65969E-03	0.578%
Base with static mode + <code>ORTHO_BASE</code>			
Displacement (<i>m</i>)	-1.85356E-06	-1.88612E-06	1.7566%
Speed (<i>m.s</i> ⁻¹)	-4.63289E-03	-4.65969E-03	0.578%

6 Summary of the results

For modeling B, the precision on displacements of the loose lead of the beam at the moment $t=0.1315s$ is correct (relative error $< 10\%$). This test thus validates the operators of non-linear transitory calculation by dynamic under-structuring.

Modeling C shows the interest of the enrichment of the base using the static modes.

The results are identical if the enriched modal base is orthogonalisé or not.