

Operator DEFI_BASE_REDUCED

The goal of the operator is to build the reduced base starting from a non-linear calculation (thermal or mechanical) or of a parametric linear calculation.

There exist two methods:

- For the non-linear problems, the operator rests on a `sd` result of the type `evol_ther` or `evol_noli` and a singular decomposition with the values (SVD) on the transient or a strategy of the incremental type POD realizes;
- For the parametric linear problems, one uses an algorithm of the `glouton` type. In this case, one defines the linear system to solve.

The operator also allows to truncate a base (primal or dual) on a reduced field (for example produced by the order `DEFI_DOMAINE_REDUIT`).

Two types of bases can be produced:

- bases known as “primal”: they are pressed on the fields of displacements for mechanics and on the fields of temperatures for thermics;
- bases known as “dual”: they are pressed on the stress fields for mechanics and on the fields of flow for thermics.

The operator produces a concept of the type `mode_empi`.

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1 Syntax

```
base = DEFI_BASE_REDUCED (
    ◇ BASE = base, [base_empi]

# Standard of operation
    ◇ OPERATION = |'POD ` , [DEFECT]
                  |' POD_INCR',
                  |' GLOUTON',
                  |' TRONCATURE',
                  |' ORTHO',

# If OPERATION=' POD_INCR'
    ◇ SHEET = /tole_incr , [R]
              /1.0E- 10 , [ DEFECT ]
]
    ◇ TABL_COOR_REDUIT = tabl_coor , [ table ]

# If OPERATION=' POD_INCR' or 'POD'
    ◇ M ODELE = model , [ model ]
    ◇ SNAPSHOT = nume_ordre , [I]

# options for the results produced by STAT_NON_LINE
    ◇ RESULT = resu, [evol_noli]
    ◇ NOM_CHAM = |'DEPL'
                |' SIEF_NOEU'

# options for the results produced by THER_NON_LINE
    ◇ RESULT = resu, [evol_ther]
    ◇ NOM_CHAM = |'TEMP'
                |' FLUX_NOEU'
    ◇ TYPE_BASE = |' 3D', [DEFECT]
                |' LINEIQUE',

# options for TYPE_BASE = 'LINEAR'
    ◇ AXIS = |' OX',
            |' OY',
            |' OZ'
    ◇ SECTION = l_grno, [l_gr_noeud]

# options of selection amongst modes
    ◇ TOLE_SVD = /tole, [R]
                /1.0E-6, [ DEFECT ]

    ◇ NB_MODE = nbmode, [I]

# If OPERATION='GLOUTON`
    ◇ ORTHO_BASE = /'NOT', [DEFECT]
                  /'YES'
    ◇ TYPE_BASE = /'STANDARD', [DEFECT]
                  /'IFS_STAB'
    ◇ NB_VARI_COEF = nbvaricoef, [I]
    ◇ TYPE_VARI_COEF = |' DIRECT ` , [DEFECT]
    ◇ VARI_PARA = F (
```

```
[para_fonc]
  ◆ NOM_PARA      = will nompara,
  ◆ VALE_PARA     = will valepara,          [R]
  ◆ VALE_INIT     = valeinit              [R]
  ),
  ◇ MATR_ASSE     = _F (
  ◆ MATRIX        = matrix ,              /[matr_adze_DEPL_R]
                                          /[matr_adze_DEPL_C]
  ◇ COEF_R        = coefr,                [R]
  ◇ COEF_C        = coefc,                [C]
  ◇ FONC_R        = foncr,                [fonction/formule]
  ◇ FONC_C        = foncc,                [fonction/formula]
  ),
  ◇ VECT_ASSE     = _F (
  ◆ VECTOR        = vector ,              [cham_no_aster]
  ◇ COEF_R        = coefr,                [R]
  ◇ COEF_C        = coefc,                [C]
  ◇ FONC_R        = foncr,                [fonction/formule]
  ◇ FONC_C        = foncc,                [fonction/formula]
  ),
  ◇ SOLVEUR       = _F (see the document [U4.50.01]),

# If OPERATION='TRUNCATION'
  ◆ MODELE_REDUIT = model,                [model]

# For all the operations
  ◇ TITLE         = title,                [l_Kn]
  ◇ INFORMATION   = /1,                    [DEFECT]
  /2,
)
```

2 Operands

The operator leaves a structure of data of type `mode_empi` (modes empirical).

2.1 Operand BASE

◇ `BASE` = `base`, [base_empi]

It is possible to enrich a base by empirical modes by the following operations. In this case, it here is provided.

2.2 Operand OPERATION

◇ `OPERATION` = | 'POD' , [DEFECT]
| ' POD_INCR' ,
| ' GLOUTON' ,
| ' TRONCATURE' ,
| ' ORTHO' ,

This keyword makes it possible to choose the manner of calculating the empirical modes:

- By a POD (`OPERATION=' POD'`): one carries out a SVD on the matrix of the snapshots containing the results on a transient. This operation is exact (within the meaning of the extraction of the empirical modes) but perhaps potentially expensive (in CPU and memory);
- By an incremental POD (`OPERATION=' POD_INCR'`): one builds the empirical base in an incremental way (see [R5.01.50]). This method is less precise than the classical POD but much less expensive. Moreover it makes it possible to enrich an empirical base existing with new results;
- By a method glouton (`OPERATION=' GLOUTON'`, to see [R5.01.50]) on parametric problems;

It is possible also of **to truncate** a base (primal or dual) on a reduced field (for example produced by the order `DEFI_DOMAINE_REDUIT`) with `OPERATION=' TRONCATURE'` or of D-orthogonaliser an existing base by the keyword `'ORTHO'`.

2.3 Operands for the strategies POD

2.3.1 Operand RESULT

◇ `RESULT` = `resu`,

Name of the structure of data result to analyze to generate the reduced base. Two types of possible results: `evol_noli` or `evol_ther`.

Limitations of use:

- Function only in 3D (thermal and mechanical);
- Cannot use limiting conditions of Dirichlet by dualisation (`AFFE_CHAR_MECA` or `AFFE_CHAR_THER`). It is necessary to use limiting conditions of Dirichlet per elimination (`AFFE_CHAR_CINE`).

2.3.2 Operand MODEL

◇ `MODEL` = `model` ,

When the result given by the keyword `RESULT` does not contain the relative information with the model (this perhaps case when one handles it before with the orders `CREA_RESU` or `LIRE_RESU`), this keyword makes it possible to define *explicitly* the model.

2.3.3 Operand `SNAPSHOT`

```
◇ SNAPSHOT = nume_snap ,
```

This keyword makes it possible to filter the moments in the R é sultat given by the keyword `RESULT` to generate the matrix of the snapshots. The selected moments are referred by their sequence number.

2.3.4 Operand `TABL_COOR_REDUIT`

```
◇ TABL_COOR_REDUIT = tabl_coor ,
```

Lorsqu' one calculates an empirical base by the method of the incremental POD to enrich an already existing base, it is necessary to have the reduced coordinates of preceding calculation. These coordinates are stored in a structure of data `table` of name '`COOR_REDUIT`' who is attached to the empirical base. One can recover it via the operator `RECU_TABLE` . For example:

```
coorredp=RECU_TABLE (CO=base, NOM_TABLE=' COOR_REDUIT')
```

But if you recover the empirical base previously calculated by an operator like `LIRE_RESU` (in particular with format `MED`), this table is not available. The operator `TABL_COOR_REDUIT` thus allows to give it to `DEFI_BASE_REDUITE`.

It is thus necessary to have saved this table upstream at the same time as the empirical base (by one `IMPR_TABLE`), then to recover it (by one `LIRE_TABLE`) to give it to `DEFI_BASE_REDUITE`. A typical succession of orders is thus the following one:

1/ Creation of a first reduced base

- non-linear calculation
- creation of the base with `DEFI_BASE_REDUITE`
- recovery of the table of the coordinates reduced with `RECU_TABLE`
- safeguard of the empirical base by `IMPR_RESU`
- safeguard of the table of the coordinates reduced by `IMPR_TABLE`

2/ Enrichment bases to reduce

- non-linear calculation
- reading of the preceding empirical base by `LIRE_RESU`
- reading of the table of the reduced coordinates preceding by `LIRE_TABLE`
- enrichment of the base reduced by `DEFI_BASE_REDUITE` by giving the preceding base (keyword `BASE`) and the table of the reduced coordinates preceding (keyword `TABL_COOR_REDUIT`)

2.3.5 Operand `NOM_CHAM`

```
◆ NOM_CHAM =| 'DEPL'  
            | 'SIEF_NOEU'  
            | 'TEMP'  
            | 'FLUX_NOEU'
```

One specifies the type of basic field reduced:

- '`DEPL`' or '`SIEF_NOEU`' if the structure of data is of type `evol_noli` ;
- '`TEMP`' or '`FLUX_NOEU`' if the structure of data is of type `evol_ther`.

2.3.6 Operand `TYPE_BASE`

```
◇ TYPE_BASE =| '3D',  
              | 'LINEAR',
```

One specifies the basic type reduced.

The linear case is specific to the digital simulation of welding. This case requires to specify the axis of welding and information concerning the section of the welded zone, perpendicular to the axis of welding.

2.3.7 OperandS **AXIS** and **SECTION**

OperandS usedS in the linear case (specific to the digital simulation of welding).

```
◆  AXIS    =| ' OX',  
      | ' OY',  
      | ' OZ',
```

Operand allowing to specify the axis of welding.

```
◆  SECTION = l_grno,
```

Operand allowing to specify the group of nodes contained in the first section of the grid of the welded zone.

Note:

These operands make it possible to define a local classification used for the calculation of the reduced modes.

2.3.8 OperandS **NB_MODE** / **TOLE_SVD**

```
◇  TOLE_SVD = sheet
```

Désigne the tolerance retained for the SVD. The value by default is of 1.0E-6.

The selected modes are those whose singular value is higher than `sheet X sing_maxi` where `sing_maxi` is the maximum singular value given by the SVD.

Notice : the incremental POD (`OPERATION=' POD_INCR'`) fact also a SVD but not on the matrix of the stereotypes. This parameter is thus also useful in this case.

```
◇  NB_MODE  = nbmode
```

NRshade of modes retained for the construction of the reduced base.

The user must inform only one of the two operands to fix the number of modes retained for the construction of BESA reduced.

2.3.9 Operand **SHEET**

```
◇  SHEET    = /tole_incr, [R]  
              /1.0E-10, [DEFECT]
```

This parameter makes it possible to regulate the precision of the incremental POD.

2.4 Operands for the strategies **GLOUTON**

Method `OPERATION=' GLOUTON'` allows to build an empirical base on a parameterized problem. The basic principle is to build the linear system which solves the problem concerned and to give the list of the parameters which vary. The empirical base is then built by an algorithm of the type Glouton (greedy algorithm) to which it is necessary to provide the variation of the parameters.

The linear system will be written as follows:

$$\sum_{i=1}^{n_m} \alpha_i(\mathcal{Y}_{j=1, n_p}) \mathbf{M}_i = \sum_{i=1}^{n_v} \beta_i(\mathcal{Y}_{j=1, n_p}) \mathbf{V}_i \quad (1)$$

It contains n_m assembled matrices \mathbf{M}_i (real or complex). These matrices can be built in a classical way in code_aster (CALC_MATR_ELEM and ASSE_MATRICE for example). In front of each matrix, there is a coefficient $\alpha_{i=1, n_m}$, which is either constant (reality or complex), or a function or a formula (real or complex) which depends to the maximum of $\mathcal{Y}_{j=1, n_p}$ parameters.

Lastly, the second member \mathbf{V} is also a linear combination of n_v vectors (real or complex) with a coefficient $\beta_{i=1, n_v}$, which is either constant (reality or complex), or a function or a formula (real or complex) which depends to the maximum of $\mathcal{Y}_{j=1, n_p}$ parameters.

To build the empirical base, it is necessary to traverse space parameters what the user defined in the §2.4.2.

2.4.1 Operands MATR_ASSE and VECT_ASSE

These operands will build the linear system to solve.

```

◇ MATR_ASSE          = _F (
  ◆ MATRIX           = matrix ,                / [matr_adze_DEPL_R]
                                          / [matr_adze_DEPL_C]
  ◇ COEF_R           = coefr ,                [R]
  ◇ COEF_C           = coefc ,                [C]
  ◇ FONC_R           = foncr ,                [fonction/formule]
  ◇ FONC_C           = foncc ,                [fonction/formula] ,

```

ON gives the list of the assembled matrices \mathbf{M}_i by the keyword factor MATR_ASSE. The name of the matrix (coming for example from the order ASSE_MATRICE) is given in MATRIX.

One chooses then the coefficient in front of each matrix. This coefficient is constant (reality by COEF_R or complex by COEF_C), that is to say a function (real by FONC_R or complex by FONC_C). In the case of a function, it must depend on the parameters whose list (variation) is given by the keyword factor VARI_PARA (see § 2.4.2).

```

◇ VECT_ASSE         = _F (
  ◆ VECTOR          = vector ,                [cham_no_aster]
  ◇ COEF_R          = coefr ,                [R]
  ◇ COEF_C          = coefc ,                [C]
  ◇ FONC_R          = foncr ,                [fonction/formule]
  ◇ FONC_C          = foncc ,                [fonction/formula] ,

```

These keywords define the second member \mathbf{V} by the keyword VECT_ASSE . One chooses then the coefficient in front of each vector . This coefficient is constant (reality by COEF_R or complex by COEF_C), that is to say a function (real by FONC_R or complex by FONC_C). In the case of a function, it must depend on the parameters whose list (variation) is given by the keyword factor VARI_PARA (see § 2.4.2).

2.4.2 Operands VARI_PARA , NB_VARI_COEF and TYPE_VARI_COEF

These operands define parametric space traversed to build the empirical base.

```

◆ NB_VARI_COEF     = nbvaricoef ,            [ I ]
◇ TYPE_VARI_COEF   = | ' DIRECT ' ,         [DEFECT]

```

NB_VARI_COEF give the number of parameters when parametric space is traversed. The keyword TYPE_VARI_COEF allows to say that one will give *explicitly* the list of the values of the parameters (only mode available for the moment).


```
◇ VARI_PARA = _F (
  ◆ NOM_PARA = will nompara, [para_fonc]
  ◆ VALE_PARA = will valepara, [R ]
  ◆ VALE_INIT = valeinit [R]
),
```

LE keyword factor `VARI_PARA` give the list of the parameters $\gamma_{j=1,n_p}$ and their values. For each occurrence, one gives the name of the parameter in `NOM_PARA`. This parameter is inevitably used in the coefficients $\alpha_{i=1,n_m}$ in front of the matrices. For each parameter, one gives the list of his values by `VALE_PARA`. The length of the vector `VALE_PARA` is inevitably equal to `NB_VARI_COEF`. Also should be given an initial value `VALE_INIT` (which initializes the algorithm glouton).

2.4.3 Operand SOLVEUR

This keyword gives the parameters of the solver used (see [U4.50.01]). Indeed the algorithm glouton will solve a large number of times the definite linear system.

2.4.4 Operand ORTHO_BASE

```
◇ ORTHO_BASE = / 'NOT', [DEFECT]
              / 'YES'
```

This keyword allows to make a orthonormalisation of the base empirical when `ORTHO_BASE=' OUI '`. This orthonormalisation is made with an algorithm of iterative the Graam-Schmidt type (IGS) according to the version of Kahan-Parlett.

2.4.5 Operand TYPE_BASE

```
◇ TYPE_BASE = / 'STANDARD', [DEFECT]
              / 'IFS_STAB'
```

When `TYPE_BASE=' IFS_STAB '`, one creates an empirical base which will be stable when it is used for models of interaction fluid-structure (model $\{u, p, \varphi\}$ to see [R4.02.02]) in transitory dynamics. The strategy consists in building an empirical base by diagonalisation of three bases on each component (see [R5.01.50]). When this keyword is activated, a checking of the components present is made on the components of the result as starter.

2.5 Other operations

2.5.1 Truncation of a base

```
◇ OPERATION = 'TRUNCATION'
◆ MODELE_REDUIT = model, [model]
```

Method `OPERATION='TRUNCATION'` allows to truncate an empirical base on a model more restricted than that which was used to build the base. This operation is essential when one shows very-reduction of model (keyword `DOMAINE_REDUIT` in `STAT_NON_LINE` and `THER_NON_LINE`).

The keyword `BASE` as starter gives the empirical base to truncate. The keyword `MODELE_REDUIT` give the model on which the base will be truncated. It is indeed of the model and not the grid.

2.5.2 Orthostandardisation of a base

```
◇ OPERATION = 'ORTHO'
◇ ALPHA = 0,717, [DEFECT]
          alpha [R]
```

Method `OPERATION='ORTHO'` allows orthonormaliser an empirical base. A standard procedure POD makes it possible to obtain an orthonormal base. On the other hand, it can arrive in certain cases that a base is not orthonormal:

- when one uses an algorithm of the glouton type
- when one uses an algorithm of the incremental type POD with certain values of parameters too "slackened"
- when the initial system to solve is badly conditioned

The keyword `BASE` as starter gives the empirical base to orthonormaliser.

This orthonormalisation is made with an algorithm of iterative the Graam-Schmidt type (IGS) according to the version of Kahan-Parlett. The parameter `ALPHA` allows to regulate the algorithm. The larger it is, the less the algorithm will reiterate but more the orthonormalisation will be imperfect.

3 Examples of use

Example of use of the incremental mode by enrichment (OPERATION=' POD_INCR'):

```
mat1 = AFFE_MATERIAU (AFFE=_F (TOUT=' YES', MATER=acier1))
resu1 = STAT_NON_LINE (CHAM_MATER = mat1,...)
model = DEFI_BASE_REDUITE (RESULTAT=resu1,
                           OPERATION=' POD',
                           NOM_CHAM=' DEPL')
mat2 = AFFE_MATERIAU (AFFE=_F (TOUT=' YES', MATER=acier2))
resu2 = STAT_NON_LINE (CHAM_MATER = mat2,...)
model = DEFI_BASE_REDUITE (reuse=model,
                           OPERATION=' POD_INCR',
                           RESULTAT=resu2,
                           NOM_CHAM=' DEPL')
```

The empirical base `model` was built on two sets of parameters materials.

Note:

- In the example above, the first `DEFI_BASE_REDUITE` could have been used in incremental mode (`OPERATION=' POD_INCR'`);
- With a very weak tolerance (keyword `SHEET`), the incremental mode tends towards a classical SVD.