

## SDNL104 - transitory Under-structuring nonlinear: shock of a beam on 1 support

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### Summary:

The scope of application of this test relates to the dynamics of the structures, and more particularly the calculation of transitory answer nonlinear per dynamic under-structuring.

It is a question of calculating the nonlinear transitory answer of a beam in inflection with shock on a support elastic and subjected to a constant force as from the initial moment. The beam is modelled by elements of the type `POU_D_E` (model beam of Euler).

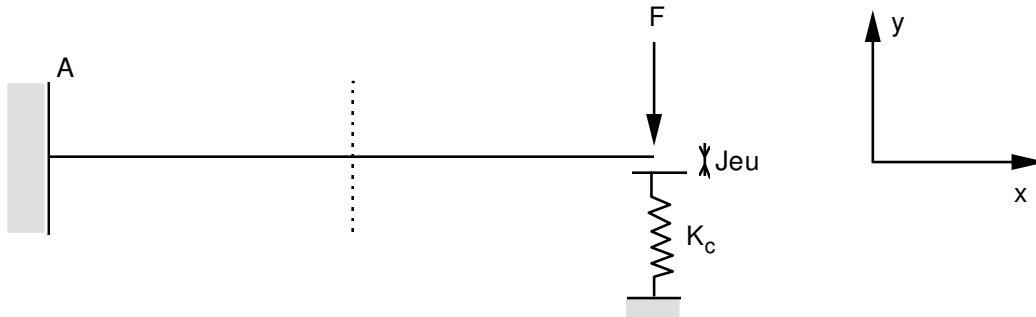
The results of reference result from a direct transitory calculation on the model not substructure, by using the operator `DYNA_NON_LINE`. This test thus makes it possible to validate the computational tools of response transitory by under - structuring, in the case of the taking into account of non-linearities of type shock on a fixed obstacle.

One also checks the interest of the static modes to enrich the base by projection and the orthogonalisation of the base.

## 1 Problem of reference

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### 1.1 Geometry



The length of the beam is worth:  $L = 1 \text{ m}$

The section of the beam is full circular of ray:  $R = 0.1 \text{ m}$

The game between the beam and the elastic support is worth:  $J = 1 \cdot 10^{-4} \text{ m}$

### 1.2 Material properties

$$E = 1.10^{10} \text{ Pa}$$

$$\nu = 0.3$$

$$\rho = 1.10^6 \text{ kg/m}^3$$

The stiffness within the competence of contact is worth:  $K_c = 1.10^8 \text{ N/m}$

### 1.3 Boundary conditions and loadings

On all the structure:  $DX = DZ = DRY = DRX = 0$ .

At the point A :  $DY = DRZ = 0$ .

At the loose lead of the beam: as from the moment  $t = 0 \text{ s}$ ,  $F_y = -1000 \text{ N}$

### 1.4 Initial conditions

Structure initially at rest.

## 2 Reference solution

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### 2.1 Method of calculating used for the reference solution

The reference solution is given by a direct transitory calculation using the operator `DYNA_NON_LINE` (modeling A).

### 2.2 Results of reference

Value displacements, speed of the loose lead of the beam according to the direction  $Y$  at the moment when their values are maximum, i.e. with  $t=0.1315\text{ s}$  for displacement and with  $t=0.1566\text{ s}$  for speed.

	Displacement ( $m$ )	Speed ( $m.s^{-1}$ )
Diagram of Newmark	-1.853E-06	-0.00463

### 2.3 Uncertainty on the solution

Digital solution.

## 3 Modeling A

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### 3.1 Characteristics of modeling

The beam is with a grid in segments to which are affected of the elements of the type `POU_D_E`.

### 3.2 Characteristics of the grid

Many nodes: 11

Many meshes and types: 10 `SEG2`

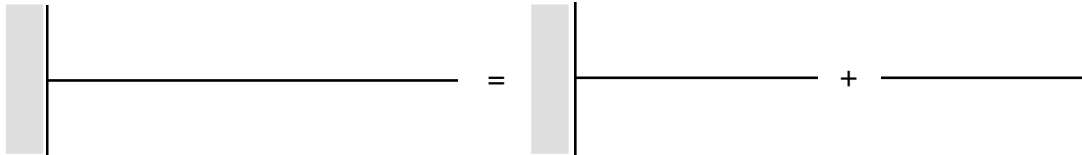
### 3.3 Actual values: references for modeling B

Identification	Aster
<b>Diagram of Newmark</b>	
Displacement ( $m$ )	-1.853E-06
Speed ( $m.s^{-1}$ )	-0.00463

## 4 Modeling B

### 4.1 Characteristics of modeling

The beam is cut out in 2 parts of equal size. Each substructure considered is with a grid in segments to which are affected of the elements of the type `POU_D_E`.



The structure is studied using the method of under-structuring with interfaces of the type “Craig - Bampton” (blocked interfaces).

The base of the first 5 clean modes of the complete structure is calculated by under - structuring. Then, the transitory problem, project on this basis, are solved by the transitory operator of calculation by modal recombination.

### 4.2 Characteristics of the grid

Many nodes: 6

Many meshes and types: 5 `SEG2`

### 4.3 Sizes tested and results

Identification	Reference	Aster	% difference
<b>Diagram of integration of Euler</b>			
Displacement ( $m$ )	-1.85356E-06	-1.71889E-06	7.265%
Speed ( $m.s^{-1}$ )	-4.63289E-3	-4.486745E-3	3.154%
<b>Diagram of Devogelaere</b>			
Displacement ( $m$ )	-1.85356E-06	-1.71881E-06	7.269%
Speed ( $m.s^{-1}$ )	-4.63289E-3	-4.486672E-3	3.156%
<b>Diagram with step of adaptive time of order 2</b>			
Displacement ( $m$ )	-1.85356E-06	-1.71880E-06	7.270%
Speed ( $m.s^{-1}$ )	-4.63289E-3	-4.486748E-3	3.154%

## 5 Modeling C

### 5.1 Characteristics of modeling

The beam is with a grid with elements of the type `POU_D_E`.

The transitory problem is solved in a direct way on various basic types of projection.

With the problem is dealt for four types of projection:

- on a basis made up of the first 5 normal modes;
- on a basis made up of the first 5 normal modes enriched by a static mode;
- on a basis made up of the first 5 normal modes enriched by a static mode and orthogonalisation by the base compared to the matrix by stiffness using the operand `ORTHO=' OUI '` of `DEFI_BASE_MODAL` ;
- on a basis made up of the first 5 normal modes enriched by a static mode and orthogonalisation by the base compared to the matrix by stiffness using the operand `ORTHO_BASE` of `DEFI_BASE_MODAL` .

### 5.2 Characteristics of the grid

Many nodes: 11

Many meshes and types: 10 `SEG2`

### 5.3 Actual values:

Identification	Reference	Aster	% difference
<b>Base without static mode</b>			
Displacement ( $m$ )	-1.85356E-06	-1.7223385E-06	7.07977%
Speed ( $m.s^{-1}$ )	-4.63289E-03	-4.48406E-03	3.212%
<b>Base with static mode</b>			
Displacement ( $m$ )	-1.85356E-06	-1.88612E-06	1.7566%
Speed ( $m.s^{-1}$ )	-4.63289E-03	-4.65969E-03	0.578%
<b>Base with static mode + <code>ORTHO=' OUI '</code></b>			
Displacement ( $m$ )	-1.85356E-06	-1.88612E-06	1.7566%
Speed ( $m.s^{-1}$ )	-4.63289E-03	-4.65969E-03	0.578%
<b>Base with static mode + <code>ORTHO_BASE</code></b>			
Displacement ( $m$ )	-1.85356E-06	-1.88612E-06	1.7566%
Speed ( $m.s^{-1}$ )	-4.63289E-03	-4.65969E-03	0.578%

## 6 Summary of the results

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For modeling B, the precision on displacements of the loose lead of the beam at the moment  $t=0.1315s$  is correct (relative error  $< 10\%$ ). This test thus validates the operators of non-linear transitory calculation by dynamic under-structuring.

Modeling C shows the interest of the enrichment of the base using the static modes.

The results are identical if the enriched modal base is orthogonalisé or not.