

SSNV503 - Shoe slipping on a Summarized rigid

level:

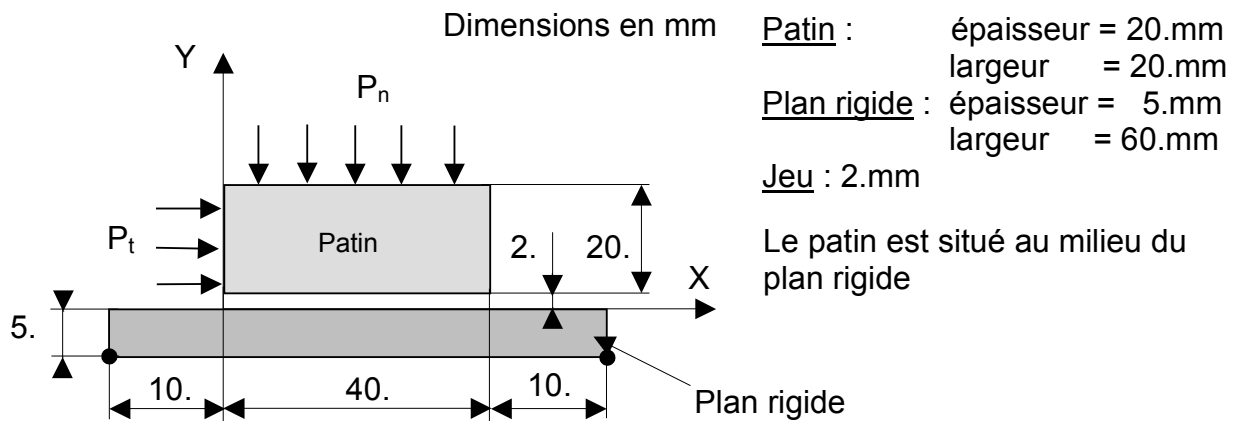
This test represents a computation of contact of a shoe slipping on a rigid level. The purpose of this test is to make it possible to validate in an unquestionable way computation of the criterion of Coulomb and the good transmission of the pressure.

The various modelizations of the contact zone tested are the following ones:

- **Modelization A** (2D): contact node-mesh, Lagrangian method for the contact and friction, geometrical clearance.
- **Modelization B** (2D): contact node-mesh with Lagrangian method and clearance defined by a function.
- **Modelization C** (2D): contact node-mesh, method Lagrangian for the contact and penalized for friction, geometrical clearance.
- **Modelization D** (2D): contact node-mesh, method penalized for the contact and friction, geometrical clearance.
- **Modelization E** (3D): contact node-mesh, method Lagrangian for the contact and penalized for friction, geometrical clearance.
- **Modelization F** (3D): contact node-mesh, method Lagrangian for the contact and penalized for friction, clearance defined by a function.
- **Modelization G** (3D): contact node-mesh, method penalized for the contact and friction, geometrical clearance.
- **Modelization H** (2D): contact node-mesh, continuous method for the contact and friction, geometrical clearance.
- **Modelization I** (3D): contact node-mesh, continuous method for the contact and friction, geometrical clearance.
- **Modelization J** (2D): contact by elements of joint, model JOINT_MECA_FROT

1 Problem of reference

1.1 Geometry



1.2 Properties of the material

Shoe:
 $E = 2.1106 \text{ N/mm}^2$ Modulus Young
 $\nu = 0$ rigid Plane Poisson's ratio

by kinematical conditions.

Contact zone:

$\mu = 0.3$ Coefficient of kinetic friction

1.3 Boundary conditions and loadings

Boundary conditions:

- All the nodes of the rigid plane are clamped.

3 cases of loading:

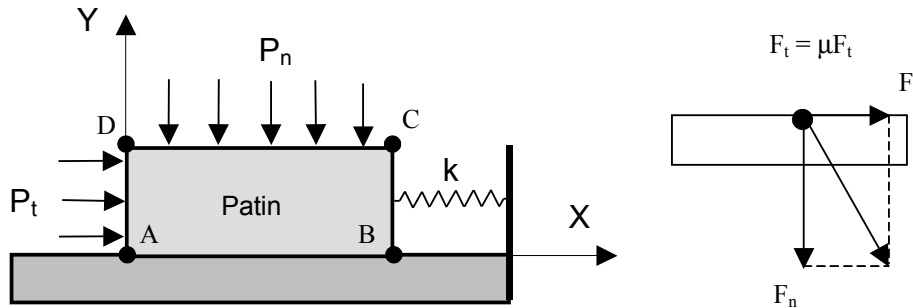
- Normal pressure $P_n = 300 \text{ N/mm}^2$
- normal Pressure $P_n = 300 \text{ N/mm}^2$ and tangential pressure $P_t = 178.2 \text{ N/mm}^2$
- normal Pressure $P_n = 300 \text{ N/mm}^2$ and tangential pressure $P_t = 181.8 \text{ N/mm}^2$

1.4 Initial conditions

None.

2 Reference solution

2.1 Method of calculating used for the reference solution



Assumption design: The strain of the shoe is neglected.

Loading 1 – normal Pressure $P_n : 300\text{N/mm}^2$

One checks:

1. Good transmission of the normal force on the level of the contact zone: the normal pressure on the level of the contact zone is equal to the pressure applied ($P_n = P_n^{contact}$)
2. That the vertical displacement of the shoe on the level of the contact zone AB is equal to clearance.

Loading 2 – normal Pressure $P_n : 300\text{N/mm}^2$ **and tangential pressure** $P_t = 178.2\text{N/mm}^2$

It is a situation of dependency. It is checked that the nodes of the shoe located in the zone of sliding (AB) do not move tangentially: $P_t = \frac{\mu P_n S_{CD}}{S_{AD}} 0.99$

Loading 3 – normal Pressure $P_n : 300\text{N/mm}^2$ **and tangential pressure** $P_t = 181.8\text{N/mm}^2$

It is a situation of sliding. It is checked that the nodes of the shoe located in the zone of sliding (AB) move of 9mm following X : $P_t = \frac{\mu P_n S_{CD}}{S_{AD}} 1.01$

Determination of the stiffness k of spring: one wants to determine the stiffness of spring according to desired displacement. At the time of the sliding, the force in spring is of:

$$F_r = F_t - \mu F_n = 0,01 \mu F_n \quad \text{with } (F_t = 181.8 \times 20, F_n = 300 \times 40)$$

$F_r = K U_t$:	force in spring
$F_t = P_t \times S_{AD}$:	tangential force
$F_n = P_n \times S_{CD}$:	normal force
U_t	:	tangential displacement
S_{AD}	:	surface
S_{DC}	:	surface

For a displacement of 9.mm the stiffness k of spring must-being of results
 $0.01 \mu F_n / 9 = 4\text{N/mm}$

2.2 of reference

- **Loading 1 (normal Pressure P_n)** : $P_n^{contact} = 300N/mm^2$
- **Loading 2 (P_n : $300N/mm^2$ and $P_t=178.2N/mm^2$)** : it is checked that there exists at least a node of the contact surface which does not slip. One test that at least one of the nodes located on the face opposed to the application of the side loading does not slip.
- **Loading 3 (P_n : $300N/mm^2$ and $P_t=181.8N/mm^2$)** : it is checked that all the nodes of contact surface slip. One tests that all the nodes located on the face opposed to the application of the side loading slip.

2.3 Uncertainties on the solution

Lower than 0,1%

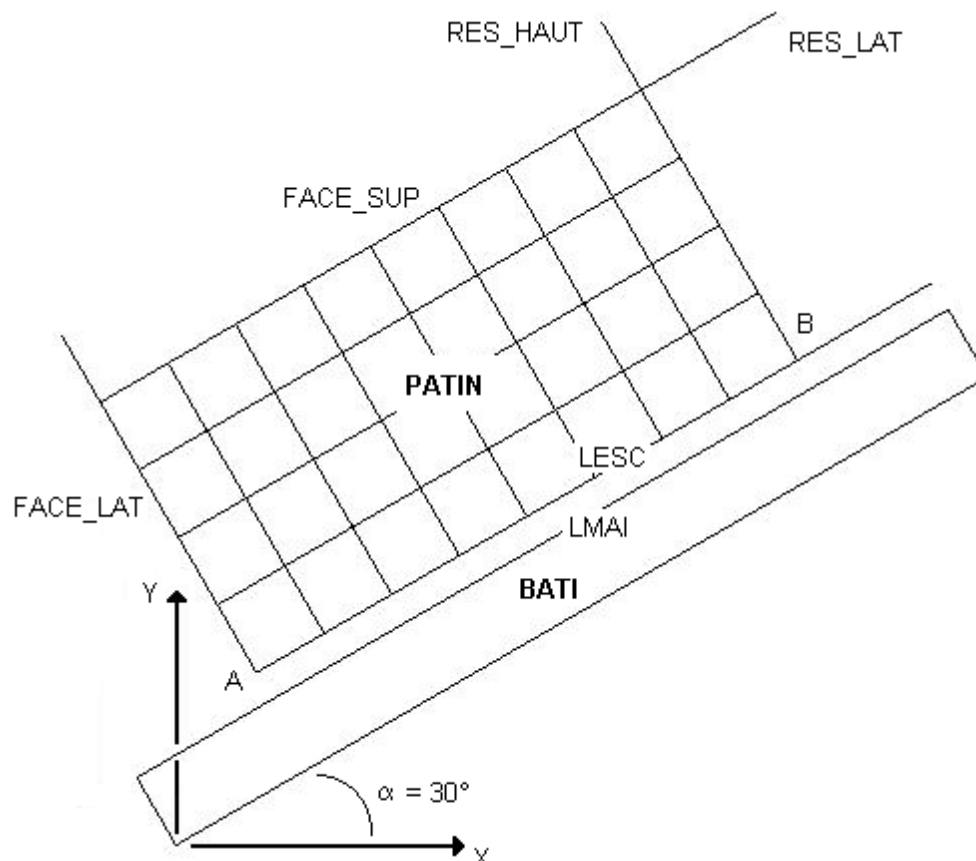
2.4 bibliographical References

Without Modelization

3 object A

3.1 Characteristic of the modelization

a modelization D_PLAN with elements QUAD4 testing the functionalities of contact node-mesh with friction treated with the Lagrangian method (discrete formulation) was implemented.



Warning : The translation process used on this website is a "Machine Translation". It may be imprecise and inaccurate in whole or in part and is provided as a convenience.

Clearance between the shoe and the frame is defined by the geometrical coordinates of the mesh.

To avoid rigid body motions, the shoe is maintained by springs of low stiffness:

$$\begin{aligned} \text{RES_LAT} &: k = 2 \text{ N/mm} \\ \text{RES_HAUT} &: k = 0,005 \text{ N/mm} \end{aligned}$$

Boundary conditions:

$$\begin{aligned} \text{Loose lead of springs: } &DX = DY = 0 . \\ \text{Frame: } &DX = DY = 0 . \end{aligned}$$

3.2 Characteristics of the mesh

Many nodes: 53
Number and types of meshes: 33 QUAD4, 32 SEG2

4 Results of the modelization A

4.1 Values tested

Standard	Identification	Reference	Tolerance
Loading 1			
Normal force of contact	1,200E+04 N	ANALYTIQUE	RELATIF – 5,00%
tangential Force of contact	0 N	ANALYTIQUE	ABSOLU – 5,00%
DX (not A)	1,000 mm	NON_REGRESSION	RELATIF – 1,00%
DY (not A)	– 1,732 mm	NON_REGRESSION	RELATIF – 1,00%
DX (not B)	1,000 mm	NON_REGRESSION	RELATIF – 1,00%
DY (not B)	– 1,732 mm	NON_REGRESSION	RELATIF – 1,00%
Loading 2			
Normal force of contact	1,200E+04 N	ANALYTIQUE	RELATIF – 5,00%
tangential Force of contact	– 3,564E+03 N	ANALYTIQUE	RELATIF – 5,00%
DX (not A)	1,000 mm	NON_REGRESSION	RELATIF – 2,3 0%
DY (not A)	– 1,732 mm	NON_REGRESSION	RELATIF – 1,00%
DX (not B)	1,000 mm	NON_REGRESSION	RELATIF – 1,00%
DY (not B)	– 1,732 mm	NON_REGRESSION	RELATIF – 1,00%
Loading 3			
Normal force of contact	1,200E+04 N	ANALYTIQUE	RELATIF – 5,00%
tangential Force of contact	– 3,624E+03 N	ANALYTIQUE	RELATIF – 5,00%
DX (not A)	8,787 mm	NON_REGRESSION	RELATIF – 1,00%
DY (not A)	2,768 mm	NON_REGRESSION	RELATIF – 1,00%
DX (not B)	8,787 mm	NON_REGRESSION	RELATIF – 1,00%
DY (not B)	2,768 mm	NON_REGRESSION	RELATIF – 1,00%

4.2 Remarks

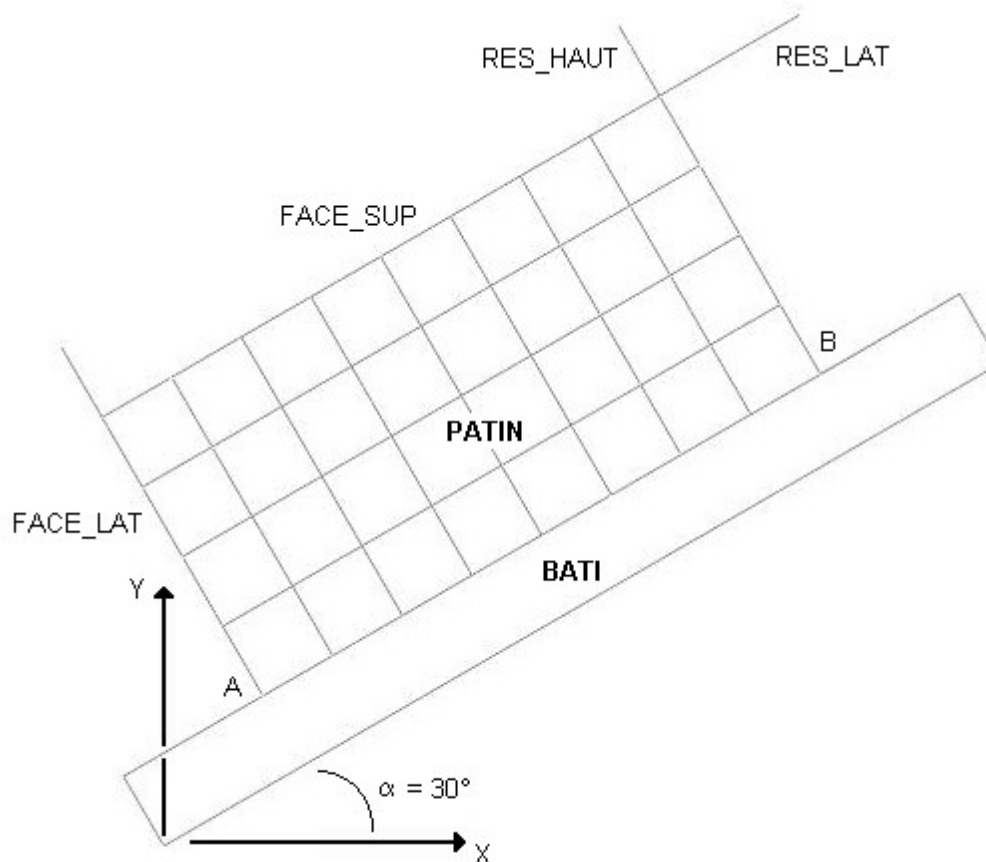
- clearance are defined in this case in a geometrical way. There is the possibility of defining it via key keys DIST_1 and DIST_2. This is done in the model according to.
- The pressures norm and tangential on the level of the contact zone are checked by testing the total force of contact in the normal and tangential meaning:

$$\begin{aligned}F_n^{CTAC} &= p_n S_{DC} = 300 * 40 * 1 = 12000N \\F_t^{CTAC} &= p_t S_{AD} = 178.2 * 20 * 1 = 35640N \quad (\text{Chargement 2}) \\F_t^{CTAC} &= p_t S_{AD} = 181.8 * 20 * 1 = 36240N \quad (\text{Chargement 3})\end{aligned}$$

5 Modelization B

5.1 Characteristic of the modelization

a modelization `D_PLAN` with elements `QUAD4` testing the functionalities of contact node-mesh with friction treated with the Lagrangian method was implemented.



Clearance between the shoe and the frame is defined by a function using key word " `DIST_2` ".

To avoid rigid body motions, the shoe is maintained by springs of low stiffness:

$$\begin{aligned}\text{RES_LAT} &: k = 2 \text{ N/mm} \\ \text{RES_HAUT} &: k = 0,005 \text{ N/mm}\end{aligned}$$

Boundary conditions:

$$\begin{aligned}\text{Loose lead of springs: } &DX = DY = 0 . \\ \text{Frame: } &DX = DY = 0 .\end{aligned}$$

5.2 Characteristics of the mesh

Many nodes: 53

Number and types of meshes: 33 `QUAD4` , 32 `SEG2`

Warning : The translation process used on this website is a "Machine Translation". It may be imprecise and inaccurate in whole or in part and is provided as a convenience.

6 Results of the modelization B

6.1 Values tested

Standard	Identification	Reference	Tolerance
Loading 1			
Normal force of contact	1,200E+04 N	ANALYTIQUE	RELATIF – 5,00%
tangential Force of contact	0 N	ANALYTIQUE	ABSOLU – 5,00%
DX (not A)	1,000 mm	NON_REGRESSION	RELATIF – 1,00%
DY (not A)	– 1,732 mm	NON_REGRESSION	RELATIF – 1,00%
DX (not B)	1,000 mm	NON_REGRESSION	RELATIF – 1,00%
DY (not B)	– 1,732 mm	NON_REGRESSION	RELATIF – 1,00%
Loading 2			
Normal force of contact	1,200E+04 N	ANALYTIQUE	RELATIF – 5,00%
tangential Force of contact	– 3,564E+03 N	ANALYTIQUE	RELATIF – 5,00%
DX (not A)	1,000 mm	NON_REGRESSION	RELATIF – 2,3 0%
DY (not A)	– 1,732 mm	NON_REGRESSION	RELATIF – 1,00%
DX (not B)	1,000 mm	NON_REGRESSION	RELATIF – 1,00%
DY (not B)	– 1,732 mm	NON_REGRESSION	RELATIF – 1,00%
Loading 3			
Normal force of contact	1,200E+04 N	ANALYTIQUE	RELATIF – 5,00%
tangential Force of contact	– 3,624E+03 N	ANALYTIQUE	RELATIF – 5,00%
DX (not A)	8,787 mm	NON_REGRESSION	RELATIF – 1,00%
DY (not A)	2,768 mm	NON_REGRESSION	RELATIF – 1,00%
DX (not B)	8,787 mm	NON_REGRESSION	RELATIF – 1,00%
DY (not B)	2,768 mm	NON_REGRESSION	RELATIF – 1,00%

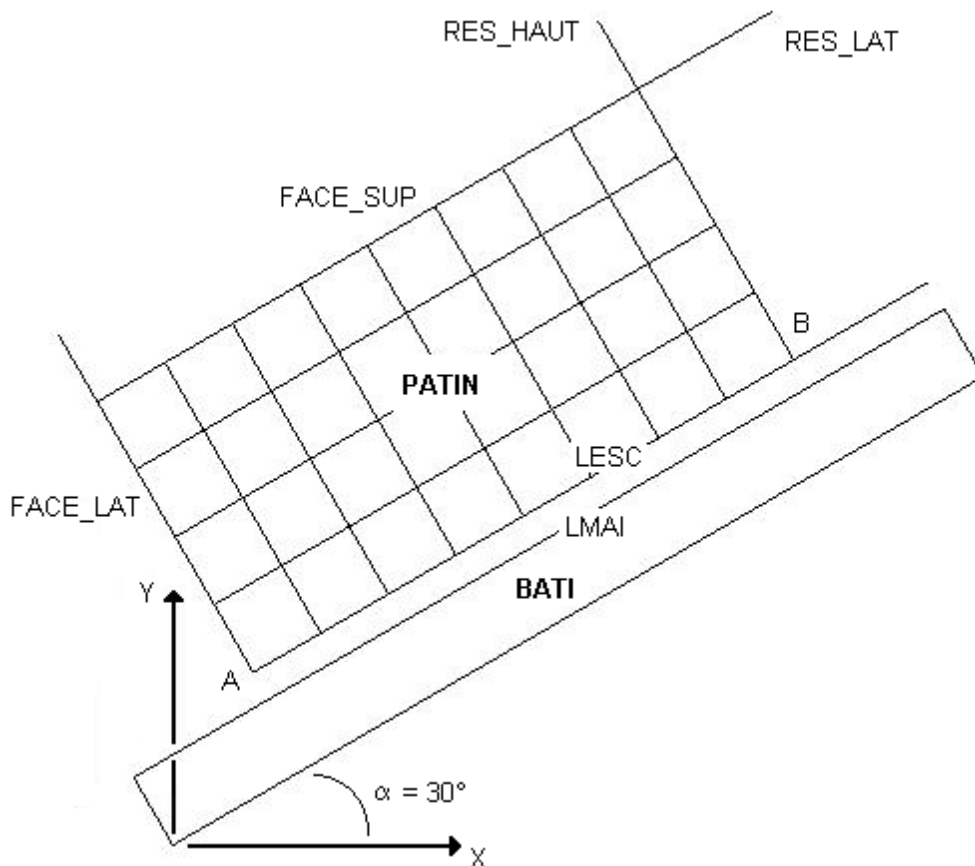
6.2 Remark

clearance are defined in this case by a function. There is no difference with the model preceding where clearance is defined in a geometrical way.

7 Modelization C

7.1 Characteristic of the modelization

a modelization D_PLAN with elements QUAD4 testing the functionalities of contact node-mesh with friction treated with the method Lagrangian for the contact and penalized for friction was implemented.



Clearance between the shoe and the frame is defined by the geometrical coordinates of the mesh.

To avoid rigid body motions, the shoe is maintained by springs of low stiffness:

RES_LAT : $k = 2 \text{ N/mm}$
RES_HAUT : $k = 0,005 \text{ N/mm}$

Boundary conditions:

Loose lead of springs: $DX = DY = 0$.
Frame: $DX = DY = 0$.

7.2 Characteristics of the mesh

Many nodes: 53
Number and types of meshes: 33 QUAD4, 32 SEG2

8 Results of the modelization C

8.1 Values tested

Standard	Identification	Reference	Tolerance
Loading 1			
Normal force of contact	1,200E+04 N	ANALYTIQUE	RELATIF - 5,00%
tangential Force of contact	0 N	ANALYTIQUE	ABSOLU - 5,00%
DX (not A)	1,000 mm	NON REGRESSION	RELATIF - 1,00%
DY (not A)	- 1,732 mm	NON REGRESSION	RELATIF - 1,00%
DX (not B)	1,000 mm	NON REGRESSION	RELATIF - 1,00%

Warning : The translation process used on this website is a "Machine Translation". It may be imprecise and inaccurate in whole or in part and is provided as a convenience.

DY (not B)	- 1,732 mm	NON_REGRESSION	RELATIF - 1,00%
Loading 2			
Normal force of contact	1,200E+04 N	ANALYTIQUE	RELATIF - 5,00%
tangential Force of contact	- 3,564E+03 N	ANALYTIQUE	RELATIF - 5,00%
DX (not A)	1,000 mm	NON_REGRESSION	RELATIF - 2,3 0%
DY (not A)	- 1,732 mm	NON_REGRESSION	RELATIF - 1,00%
DX (not B)	1,000 mm	NON_REGRESSION	RELATIF - 1,00%
DY (not B)	- 1,732 mm	NON_REGRESSION	RELATIF - 1,00%
Loading 3			
Normal force of contact	1,200E+04 N	ANALYTIQUE	RELATIF - 5,00%
tangential Force of contact	- 3,624E+03 N	ANALYTIQUE	RELATIF - 5,00%
DX (not A)	8,787 mm	NON_REGRESSION	RELATIF - 1,00%
DY (not A)	2,768 mm	NON_REGRESSION	RELATIF - 1,00%
DX (not B)	8,787 mm	NON_REGRESSION	RELATIF - 1,00%
DY (not B)	2,768 mm	NON_REGRESSION	RELATIF - 1,00%

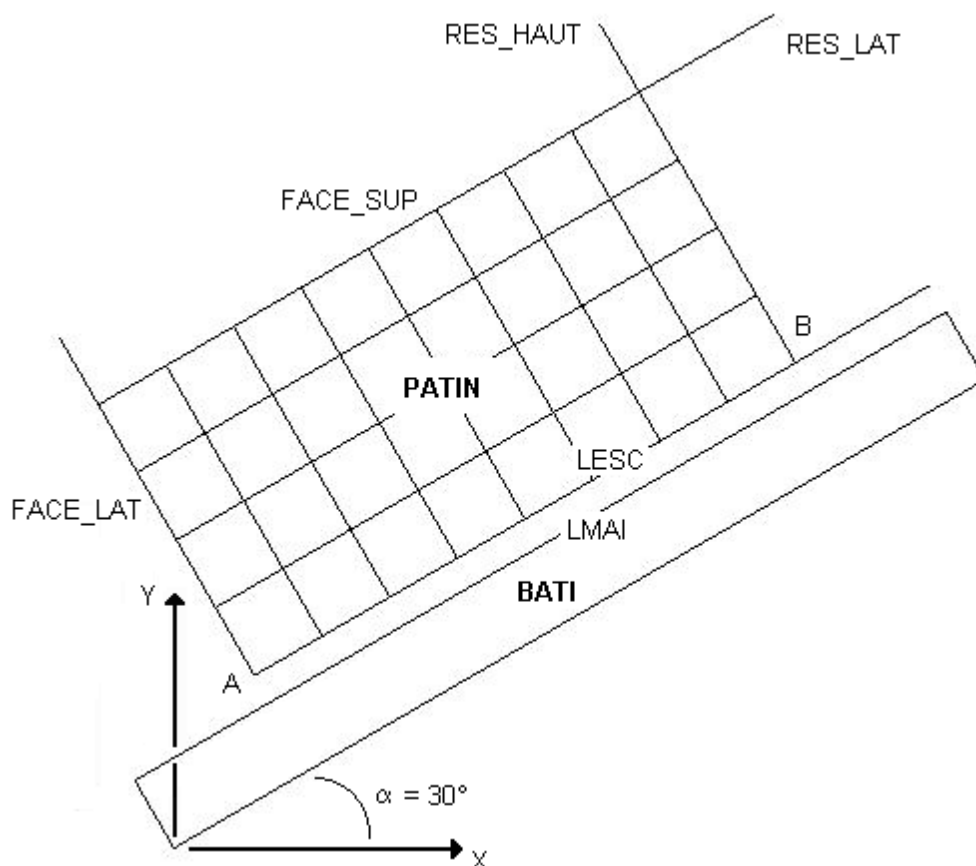
8.2 Remark

clearance are defined in this case in a geometrical way. There is the possibility of defining it via key keys `DIST_1` and `DIST_2`. After checking, this second case does not change anything with result.

9 Modelization D

9.1 Characteristic of the modelization

a modelization `D_PLAN` with elements `QUAD4` testing the functionalities of contact node-mesh with friction treated with the method penalized for the contact and friction was implemented.



Warning : The translation process used on this website is a "Machine Translation". It may be imprecise and inaccurate in whole or in part and is provided as a convenience.

Clearance between the shoe and the frame is defined by the geometrical coordinates of the mesh.

To avoid rigid body motions, the shoe is maintained by springs of low stiffness:

$$\begin{aligned} \text{RES_LAT} & : k = 2 \text{ N/mm} \\ \text{RES_HAUT} & : k = 0,005 \text{ N/mm} \end{aligned}$$

Boundary conditions:

$$\begin{aligned} \text{Loose lead of springs: } & DX = DY = 0 . \\ \text{Frame: } & DX = DY = 0 . \end{aligned}$$

9.2 Characteristics of the mesh

Many nodes: 53

Number and types of meshes: 33 QUAD4, 32 SEG2

10 Results of the modelization D

10.1 Values tested

Standard	Identification	Reference	Tolerance
Loading 1			
Normal force of contact	1,200E+04 N	ANALYTIQUE	RELATIF – 5,00%
tangential Force of contact	0 N	ANALYTIQUE	ABSOLU – 5,00%
DX (not A)	1,000 mm	NON_REGRESSION	RELATIF – 1,00%
DY (not A)	– 1,732 mm	NON_REGRESSION	RELATIF – 1,00%
DX (not B)	1,000 mm	NON_REGRESSION	RELATIF – 1,00%
DY (not B)	– 1,732 mm	NON_REGRESSION	RELATIF – 1,00%
Loading 2			
Normal force of contact	1,200E+04 N	ANALYTIQUE	RELATIF – 5,00%
tangential Force of contact	– 3,564E+03 N	ANALYTIQUE	RELATIF – 5,00%
DX (not A)	1,000 mm	NON_REGRESSION	RELATIF – 2,6 0%
DY (not A)	– 1,732 mm	NON_REGRESSION	RELATIF – 1,00%
DX (not B)	1,000 mm	NON_REGRESSION	RELATIF – 1,00%
DY (not B)	– 1,732 mm	NON_REGRESSION	RELATIF – 1,00%
Loading 3			
Normal force of contact	1,200E+04 N	ANALYTIQUE	RELATIF – 5,00%
tangential Force of contact	– 3,624E+03 N	ANALYTIQUE	RELATIF – 5,00%
DX (not A)	8,787 mm	NON_REGRESSION	RELATIF – 1,00%
DY (not A)	2,768 mm	NON_REGRESSION	RELATIF – 1,00%
DX (not B)	8,787 mm	NON_REGRESSION	RELATIF – 1,00%
DY (not B)	2,768 mm	NON_REGRESSION	RELATIF – 1,00%

10.2 Remark

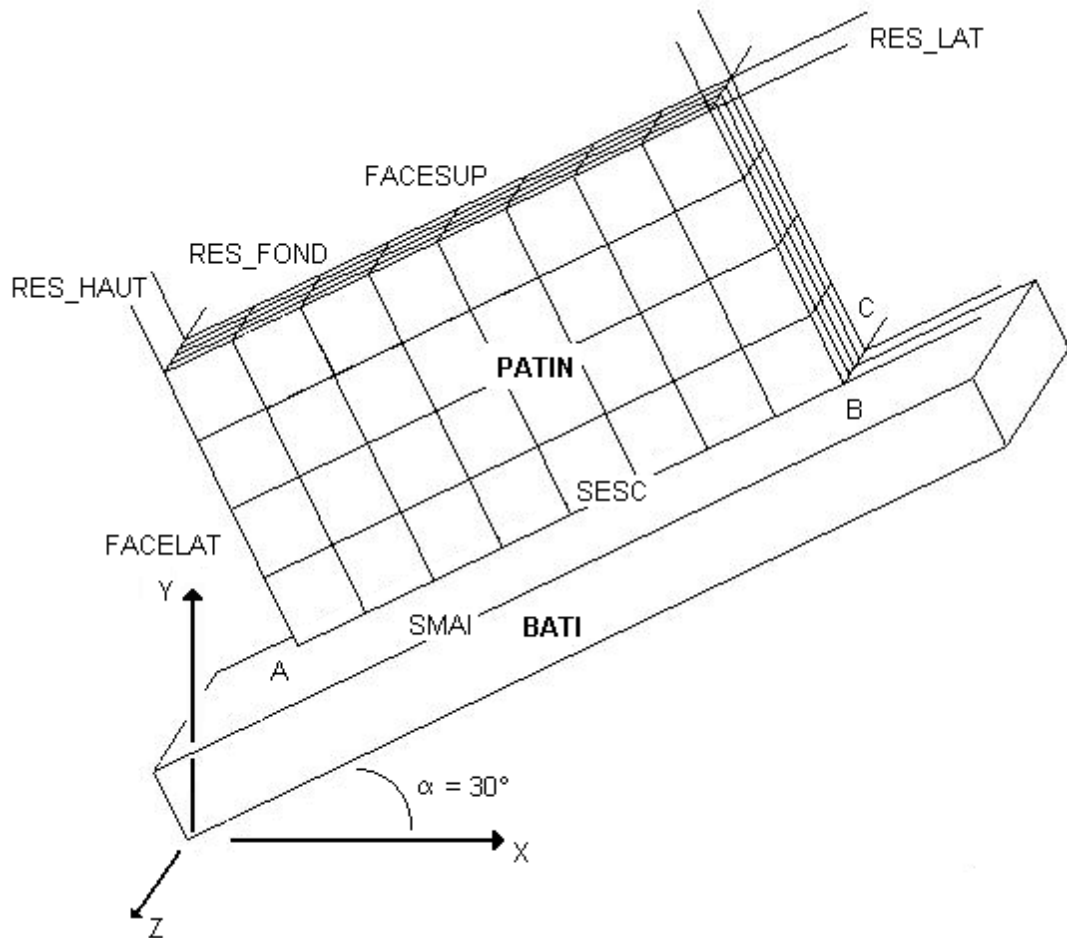
clearance are defined in this case in a geometrical way. There is the possibility of defining it via key keys DIST_1 and DIST_2. After checking, this second case does not change anything with result.

11 Modelization E

11.1 Characteristic of the modelization

a modelization 3D with elements HEXA8 testing the functionalities of contact node-mesh with friction treated with the method Lagrangian for the contact and penalized for friction was implemented.

Warning : The translation process used on this website is a "Machine Translation". It may be imprecise and inaccurate in whole or in part and is provided as a convenience.



Clearance between the shoe and the frame is defined by the geometrical coordinates of the mesh.

To avoid rigid body motions, the shoe is maintained by springs of low stiffness:

RES_LAT : $k = 1 \text{ N/mm}$
RES_FOND : $k = 1 \text{ N/mm}$
RES_HAUT : $k = 20 \text{ N/mm}$

Boundary conditions:

Loose lead of springs: $DX = DY = DZ = 0$.

Frame: $DX = DY = DZ = 0$.

11.2 Characteristics of the mesh

Many nodes: 269

Number and type of meshes: 129 HEXA8, 103 QUAD4

12 Results of the modelization E

12.1 Values tested

Standard	Identification	Reference	Tolerance
Loading 1			
Normal force of contact	2,0784E+05 N	ANALYTIQUE	RELATIF - 5,00%

Warning : The translation process used on this website is a "Machine Translation". It may be imprecise and inaccurate in whole or in part and is provided as a convenience.

tangential Force of contact	-1,2000E+05 N	ANALYTIQUE	RELATIF - 5,00%
DX (not A)	1,000 mm	NON_REGRESSION	RELATIF - 1,00%
DY (not A)	- 1,732 mm	NON_REGRESSION	RELATIF - 1,00%
DX (not B)	1,000 mm	NON_REGRESSION	RELATIF - 1,00%
DY (not B)	- 1,732 mm	NON_REGRESSION	RELATIF - 1,00%
DX (point C)	1,000 mm	NON_REGRESSION	RELATIF - 1,00%
DY (point C)	- 1,732 mm	NON_REGRESSION	RELATIF - 1,00%
DX (not D)	1,000 mm	NON_REGRESSION	RELATIF - 1,00%
DY (not D)	- 1,732 mm	NON_REGRESSION	RELATIF - 1,00%
Loading 2			
Normal force of contact	1,722E+05 N	ANALYTIQUE	RELATIF - 5,00%
tangential Force of contact	- 1,8173E+05 N	ANALYTIQUE	RELATIF - 5,00%
DX (not A)	1,000 mm	NON_REGRESSION	RELATIF - 2,6 0%
DY (not A)	- 1,732 mm	NON_REGRESSION	RELATIF - 1,00%
DX (not B)	1,000 mm	NON_REGRESSION	RELATIF - 1,00%
DY (not B)	- 1,732 mm	NON_REGRESSION	RELATIF - 1,00%
DX (point C)	1,000 mm	NON_REGRESSION	RELATIF - 1,00%
DY (point C)	- 1,732 mm	NON_REGRESSION	RELATIF - 1,00%
DX (not D)	1,000 mm	NON_REGRESSION	RELATIF - 1,00%
DY (not D)	- 1,732 mm	NON_REGRESSION	RELATIF - 1,00%
Loading 3			
Normal force of contact	1,71486E+05 N	ANALYTIQUE	RELATIF - 5,00%
tangential Force of contact	- 1,82977E+05 N	ANALYTIQUE	RELATIF - 5,00%
DX (not A)	8,794 mm	NON_REGRESSION	RELATIF - 1,00%
DY (not A)	2,768 mm	NON_REGRESSION	RELATIF - 1,00%
DX (not B)	8,794 mm	NON_REGRESSION	RELATIF - 1,00%
DY (not B)	2,768 mm	NON_REGRESSION	RELATIF - 1,00%
DX (point C)	8,794 mm	NON_REGRESSION	RELATIF - 1,00%
DY (point C)	2,768 mm	NON_REGRESSION	RELATIF - 1,00%
DX (not D)	8,794 mm	NON_REGRESSION	RELATIF - 1,00%
DY (not D)	2,768 mm	NON_REGRESSION	RELATIF - 1,00%

12.2 Remarks

- clearance are defined in this case in a geometrical way, the results are identical to those found in the preceding modelization.
- The pressures norm and tangential on the level of the contact zone are checked by testing the total force of contact in the normal and tangential meaning:

$$F_n^{CTAC} = p_n S_{DC} = 300 \times 40 \times 20 = 240000 \text{ N}$$

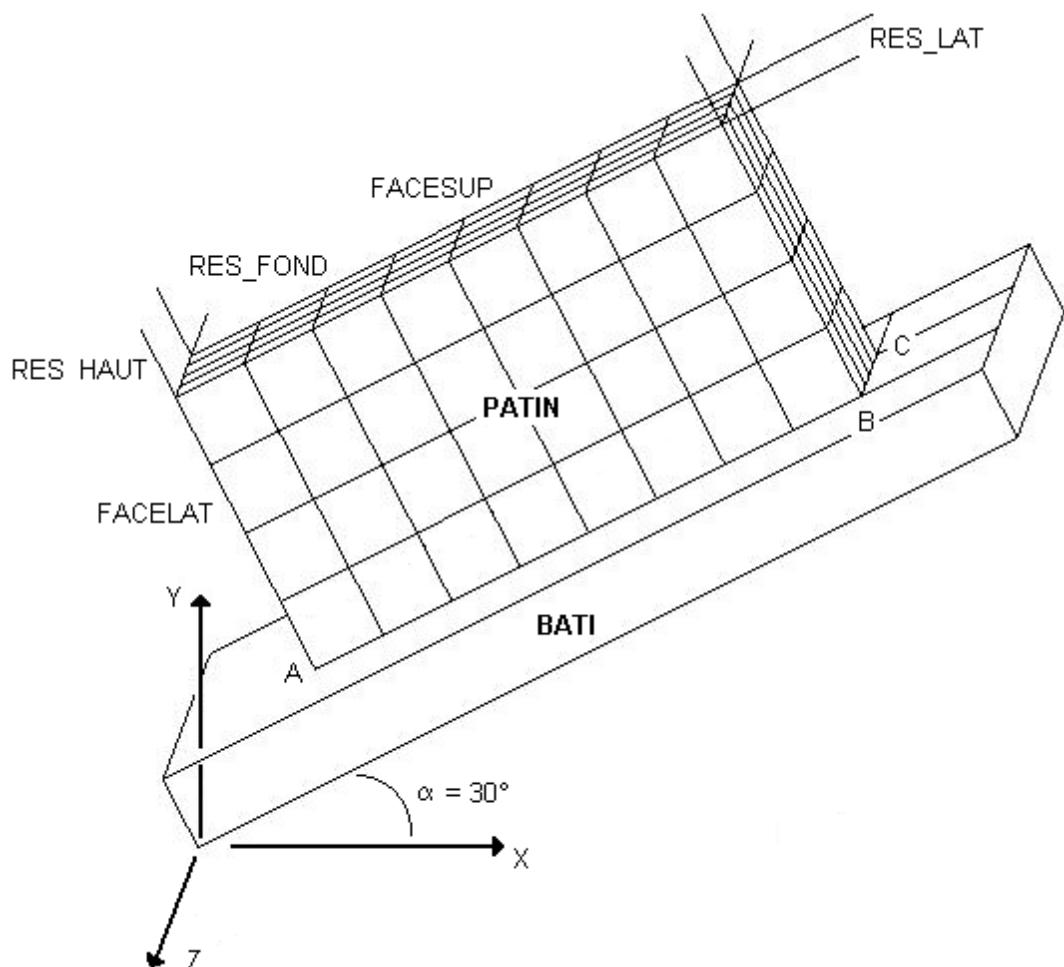
$$F_t^{CTAC} = p_t S_{AD} = 178.2 \times 20 \times 20 = 71280 \text{ N (Loading 2)}$$

$$F_t^{CTAC} = p_t S_{AD} = 181.8 \times 20 \times 20 = 72720 \text{ N (Loading 3)}$$

13 Modelization F

13.1 Characteristic of the modelization

a modelization 3D with elements HEXA8 testing the functionalities of contact node-mesh with friction treated with the method Lagrangian for the contact and penalized for friction was implemented.



Clearance between the shoe and the frame is defined by the function using key word "DIST_2".

To avoid rigid body motions, the shoe is maintained by springs of low stiffness:

$$\text{HIGH RES_} : k = 1 \text{ N/mm}$$

Warning : The translation process used on this website is a "Machine Translation". It may be imprecise and inaccurate in whole or in part and is provided as a convenience.

RES_FOND : $k = 1 \text{ N/mm}$
RES_LAT : $k = 20 \text{ N/mm}$

Boundary conditions:

Loose lead of springs: $DX = DY = DZ = 0$.

Frame: $DX = DY = DZ = 0$.

13.2 Characteristics of the mesh

Many nodes: 269

Number and type of meshes: 129 HEXA8, 103 QUAD4

14 Results of the modelization F

14.1 Values tested

Standard	Identification	Reference	Tolerance
Loading 1			
Normal force of contact	2,0784E+05 N	ANALYTIQUE	RELATIF - 5,00%
tangential Force of contact	-1,2000E+05 N	ANALYTIQUE	RELATIF - 5,00%
DX (not A)	1,000 mm	NON_REGRESSION	RELATIF - 1,00%
DY (not A)	- 1,732 mm	NON_REGRESSION	RELATIF - 1,00%
DX (not B)	1,000 mm	NON_REGRESSION	RELATIF - 1,00%
DY (not B)	- 1,732 mm	NON_REGRESSION	RELATIF - 1,00%
DX (point C)	1,000 mm	NON_REGRESSION	RELATIF - 1,00%
DY (point C)	- 1,732 mm	NON_REGRESSION	RELATIF - 1,00%
DX (not D)	1,000 mm	NON_REGRESSION	RELATIF - 1,00%
DY (not D)	- 1,732 mm	NON_REGRESSION	RELATIF - 1,00%
Loading 2			
Normal force of contact	1,722E+05 N	ANALYTIQUE	RELATIF - 5,00%
tangential Force of contact	- 1,8173E+05 N	ANALYTIQUE	RELATIF - 5,00%
DX (not A)	1,000 mm	NON_REGRESSION	RELATIF - 2,6 0%
DY (not A)	- 1,732 mm	NON_REGRESSION	RELATIF - 1,00%
DX (not B)	1,000 mm	NON_REGRESSION	RELATIF - 1,00%
DY (not B)	- 1,732 mm	NON_REGRESSION	RELATIF - 1,00%
DX (point C)	1,000 mm	NON_REGRESSION	RELATIF - 1,00%
DY (point C)	- 1,732 mm	NON_REGRESSION	RELATIF - 1,00%
DX (not D)	1,000 mm	NON_REGRESSION	RELATIF - 1,00%
DY (not D)	- 1,732 mm	NON_REGRESSION	RELATIF - 1,00%
Loading 3			
Normal force of contact	1,71486E+05 N	ANALYTIQUE	RELATIF - 5,00%
tangential Force of contact	- 1,82977E+05 N	ANALYTIQUE	RELATIF - 5,00%
DX (not A)	8,794 mm	NON_REGRESSION	RELATIF - 1,00%
DY (not A)	2,768 mm	NON_REGRESSION	RELATIF - 1,00%
DX (not B)	8,794 mm	NON_REGRESSION	RELATIF - 1,00%
DY (not B)	2,768 mm	NON_REGRESSION	RELATIF - 1,00%
DX (point C)	8,794 mm	NON_REGRESSION	RELATIF - 1,00%
DY (point C)	2,768 mm	NON_REGRESSION	RELATIF - 1,00%
DX (not D)	8,794 mm	NON_REGRESSION	RELATIF - 1,00%
DY (not D)	2,768 mm	NON_REGRESSION	RELATIF - 1,00%

14.2 Remark

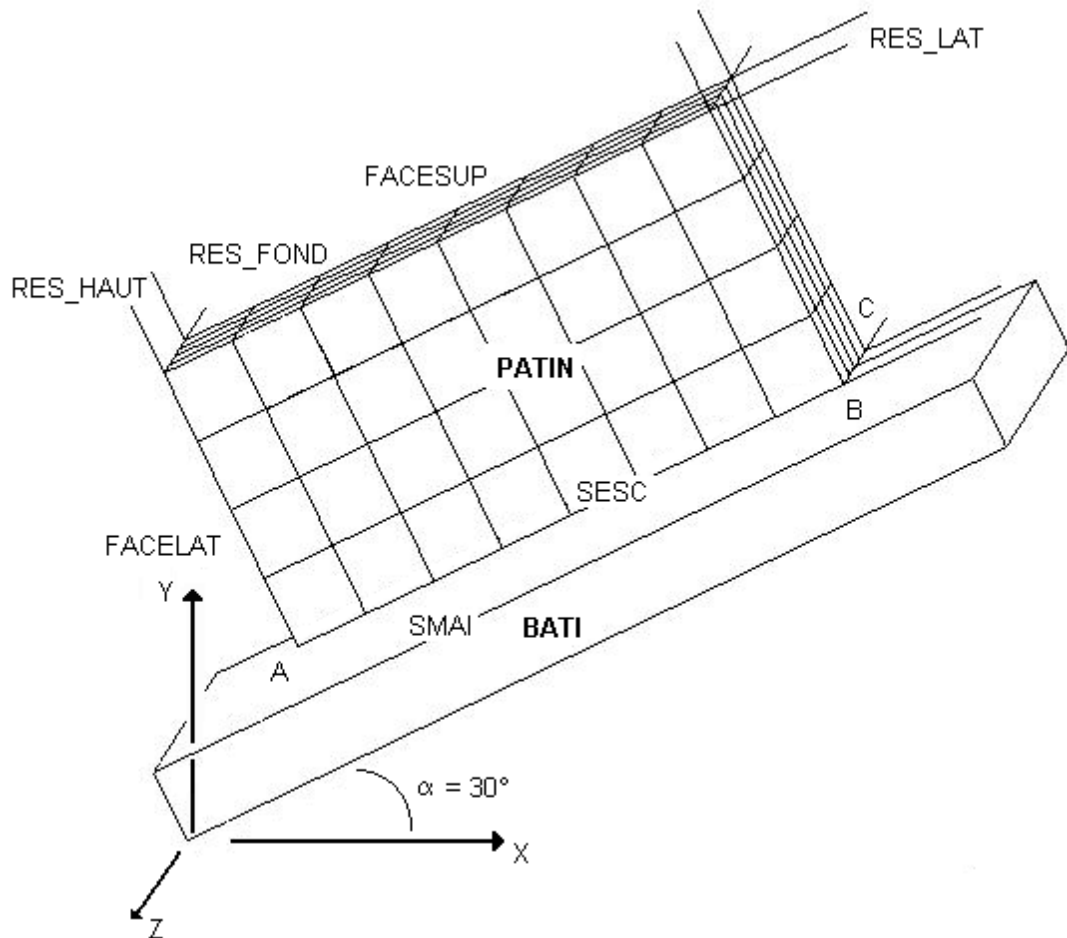
Warning : The translation process used on this website is a "Machine Translation". It may be imprecise and inaccurate in whole or in part and is provided as a convenience.

In this modelization, clearance are defined using a function, the results are identical to those found in the preceding modelization.

15 Modelization G

15.1 Characteristic of the modelization

a modelization 3D with elements HEXA8 testing the functionalities of contact node-mesh with friction treated with the method penalized for the contact and friction was implemented.



Clearance between the shoe and the frame is defined by the geometrical coordinates of the mesh.

To avoid rigid body motions, the shoe is maintained by springs of low stiffness:

HIGH RES_ : $k=1\text{ N/mm}$
RES_FOND : $k=1\text{ N/mm}$
RES_LAT : $k=20\text{ N/mm}$

Boundary conditions:

Loose lead of springs: $DX=DY=DZ=0$.
Frame: $DX=DY=DZ=0$.

15.2 Characteristics of the mesh

Many nodes: 269
Number and type of meshes: 129 HEXA8, 103 QUAD4

16 Results of the modelization G

16.1 Values tested

Standard	Identification	Reference	Tolerance
Loading 1			
Normal force of contact	2,0784E+05 N	ANALYTIQUE	RELATIF - 5,00%
tangential Force of contact	-1,2000E+05 N	ANALYTIQUE	RELATIF - 5,00%
DX (not A)	1,000 mm	NON_REGRESSION	RELATIF - 1,00%
DY (not A)	- 1,732 mm	NON_REGRESSION	RELATIF - 1,00%
DX (not B)	1,000 mm	NON_REGRESSION	RELATIF - 1,00%
DY (not B)	- 1,732 mm	NON_REGRESSION	RELATIF - 1,00%
DX (point C)	1,000 mm	NON_REGRESSION	RELATIF - 1,00%
DY (point C)	- 1,732 mm	NON_REGRESSION	RELATIF - 1,00%
DX (not D)	1,000 mm	NON_REGRESSION	RELATIF - 1,00%
DY (not D)	- 1,732 mm	NON_REGRESSION	RELATIF - 1,00%
Loading 2			
Normal force of contact	1,722E+05 N	ANALYTIQUE	RELATIF - 5,00%
tangential Force of contact	- 1,8173E+05 N	ANALYTIQUE	RELATIF - 5,00%
DX (not A)	1,000 mm	NON_REGRESSION	RELATIF - 2,3 0%
DY (not A)	- 1,732 mm	NON_REGRESSION	RELATIF - 1,00%
DX (not B)	1,000 mm	NON_REGRESSION	RELATIF - 1,00%
DY (not B)	- 1,732 mm	NON_REGRESSION	RELATIF - 1,00%
DX (point C)	1,000 mm	NON_REGRESSION	RELATIF - 1,00%
DY (point C)	- 1,732 mm	NON_REGRESSION	RELATIF - 1,00%
DX (not D)	1,000 mm	NON_REGRESSION	RELATIF - 1,00%
DY (not D)	- 1,732 mm	NON_REGRESSION	RELATIF - 1,00%
Loading 3			
Normal force of contact	1,71486E+05 N	ANALYTIQUE	RELATIF - 5,00%
tangential Force of contact	- 1,82977E+05 N	ANALYTIQUE	RELATIF - 5,00%
DX (not A)	8,794 mm	NON_REGRESSION	RELATIF - 1,00%
DY (not A)	2,768 mm	NON_REGRESSION	RELATIF - 1,00%
DX (not B)	8,794 mm	NON_REGRESSION	RELATIF - 1,00%
DY (not B)	2,768 mm	NON_REGRESSION	RELATIF - 1,00%
DX (point C)	8,794 mm	NON_REGRESSION	RELATIF - 1,00%
DY (point C)	2,768 mm	NON_REGRESSION	RELATIF - 1,00%
DX (not D)	8,794 mm	NON_REGRESSION	RELATIF - 1,00%
DY (not D)	2,768 mm	NON_REGRESSION	RELATIF - 1,00%

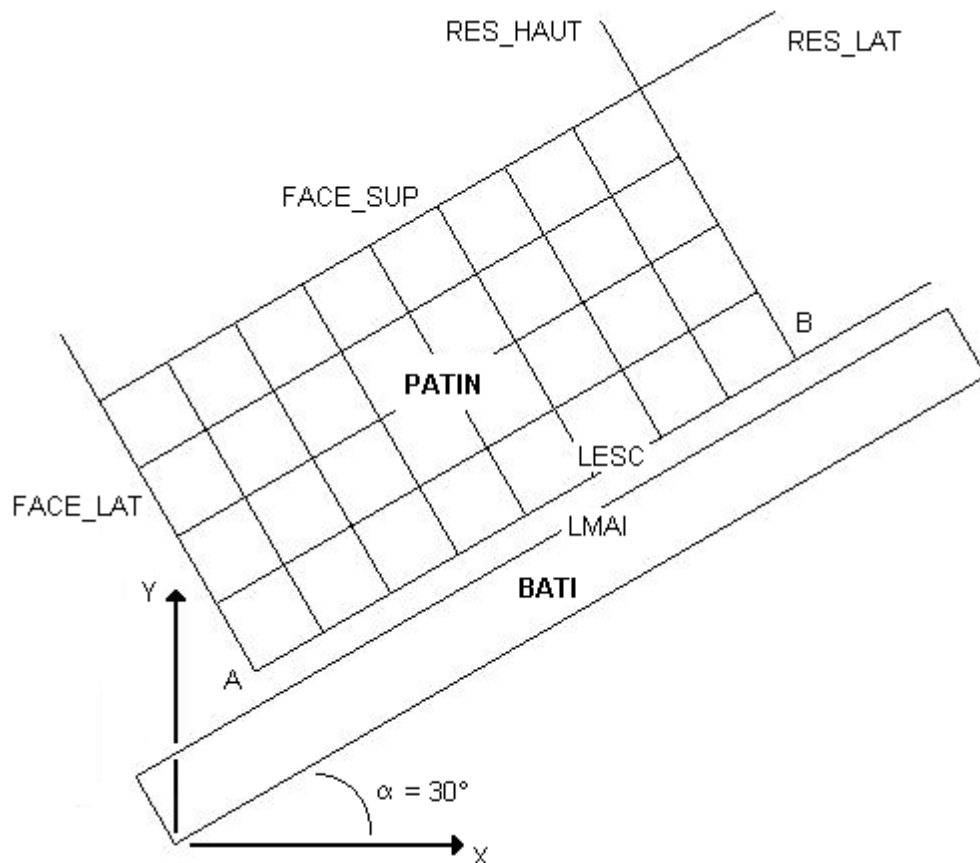
16.2 Remark

clearance are defined in this case in a geometrical way. The results are less good than those obtained with the penalization only on friction. Moreover, this method is longer.

17 Modelization H

17.1 Characteristic of the modelization

a modelization `D_PLAN` with elements `QUAD4` testing the functionalities of contact node-mesh with friction treated with the continuous method for the contact and friction was implemented.



Clearance between the shoe and the frame is defined by the geometrical coordinates of the mesh.

To avoid rigid body motions, the shoe is maintained by springs of low stiffness:

$$\begin{aligned} \text{RES_LAT} & : k = 2 \text{ N/mm} \\ \text{RES_HAUT} & : k = 0,005 \text{ N/mm} \end{aligned}$$

Boundary conditions:

$$\begin{aligned} \text{Loose lead of springs: } & DX = DY = 0 . \\ \text{Frame: } & DX = DY = 0 . \end{aligned}$$

17.2 Characteristics of the mesh

Many nodes: 53
Number and types of meshes: 33 `QUAD4`, 32 `SEG2`

18 Results of the modelization H

18.1 Values tested

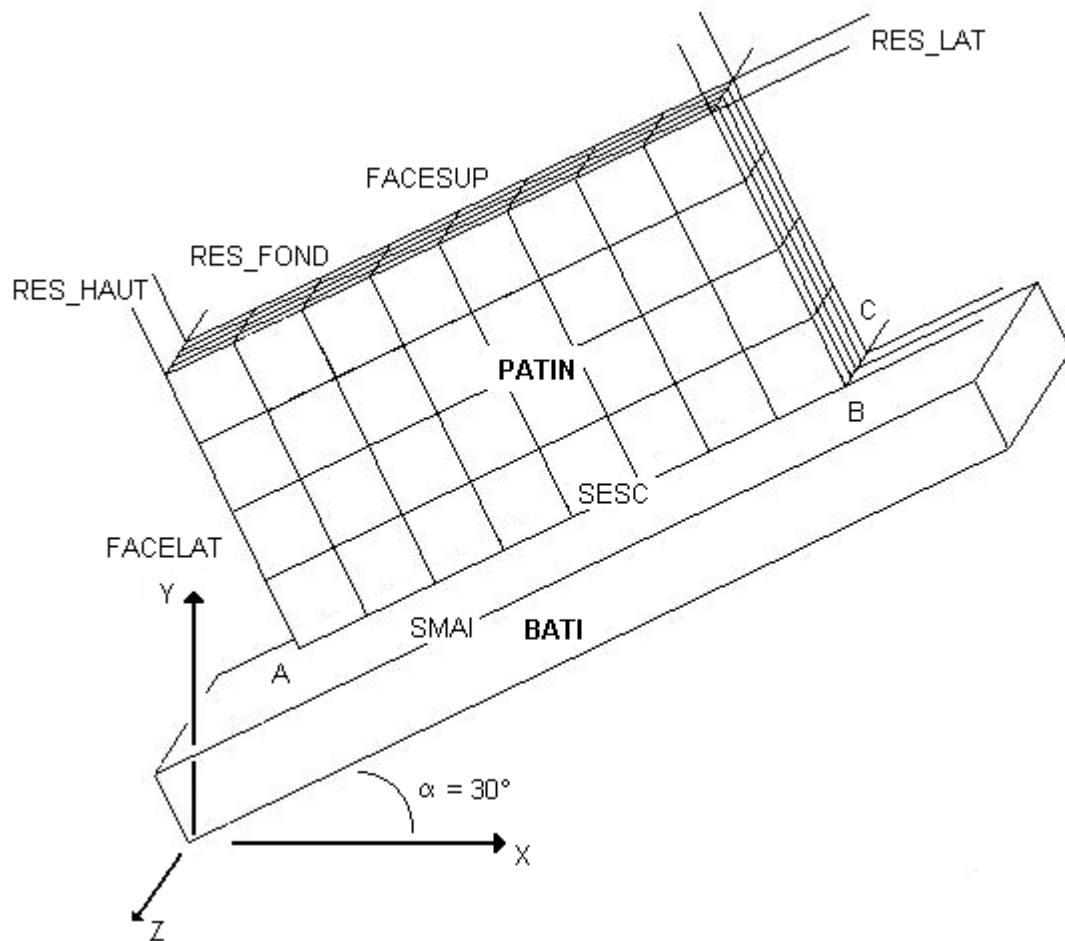
Warning : The translation process used on this website is a "Machine Translation". It may be imprecise and inaccurate in whole or in part and is provided as a convenience.

Standard	Identification	Reference	Tolerance
Loading 1			
Normal force of contact	1,200E+04 N	ANALYTIQUE	RELATIF - 5,00%
tangential Force of contact	0 N	ANALYTIQUE	ABSOLU - 5,00%
DX (not A)	1,000 mm	NON_REGRESSION	RELATIF - 1,00%
DY (not A)	- 1,732 mm	NON_REGRESSION	RELATIF - 1,00%
DX (not B)	1,000 mm	NON_REGRESSION	RELATIF - 1,00%
DY (not B)	- 1,732 mm	NON_REGRESSION	RELATIF - 1,00%
Loading 2			
Normal force of contact	1,200E+04 N	ANALYTIQUE	RELATIF - 5,00%
tangential Force of contact	- 3,564E+03 N	ANALYTIQUE	RELATIF - 5,00%
DX (not A)	1,000 mm	NON_REGRESSION	RELATIF - 2,6 0%
DY (not A)	- 1,732 mm	NON_REGRESSION	RELATIF - 1,00%
DX (not B)	1,000 mm	NON_REGRESSION	RELATIF - 1,00%
DY (not B)	- 1,732 mm	NON_REGRESSION	RELATIF - 1,00%
Loading 3			
Normal force of contact	1,200E+04 N	ANALYTIQUE	RELATIF - 5,00%
tangential Force of contact	- 3,624E+03 N	ANALYTIQUE	RELATIF - 5,00%
DX (not A)	8,787 mm	NON_REGRESSION	RELATIF - 1,00%
DY (not A)	2,768 mm	NON_REGRESSION	RELATIF - 1,00%
DX (not B)	8,787 mm	NON_REGRESSION	RELATIF - 1,00%
DY (not B)	2,768 mm	NON_REGRESSION	RELATIF - 1,00%

19 Modelization I

19.1 Characteristic of the modelization

a modelization 3D with elements HEXA 8 testing the functionalities of contact node-mesh with friction treated with the continuous method for the contact and friction was put in work.



Clearance between the shoe and the frame is defined by the geometrical coordinates of the mesh.

To avoid rigid body motions, the shoe is maintained by springs of low stiffness:

HIGH RES_ : $k = 1 \text{ N/mm}$
RES_FOND : $k = 1 \text{ N/mm}$
RES_LAT : $k = 20 \text{ N/mm}$

Boundary conditions:

Loose lead of springs: $DX = DY = DZ = 0$.

Frame: $DX = DY = DZ = 0$.

19.2 Characteristics of the mesh

Many nodes: 269

Number and type of meshes: 129 HEXA8, 103 QUAD4

20 Results of the modelization I

20.1 Values tested

Standard	Identification	Reference	Tolerance
Loading 1			

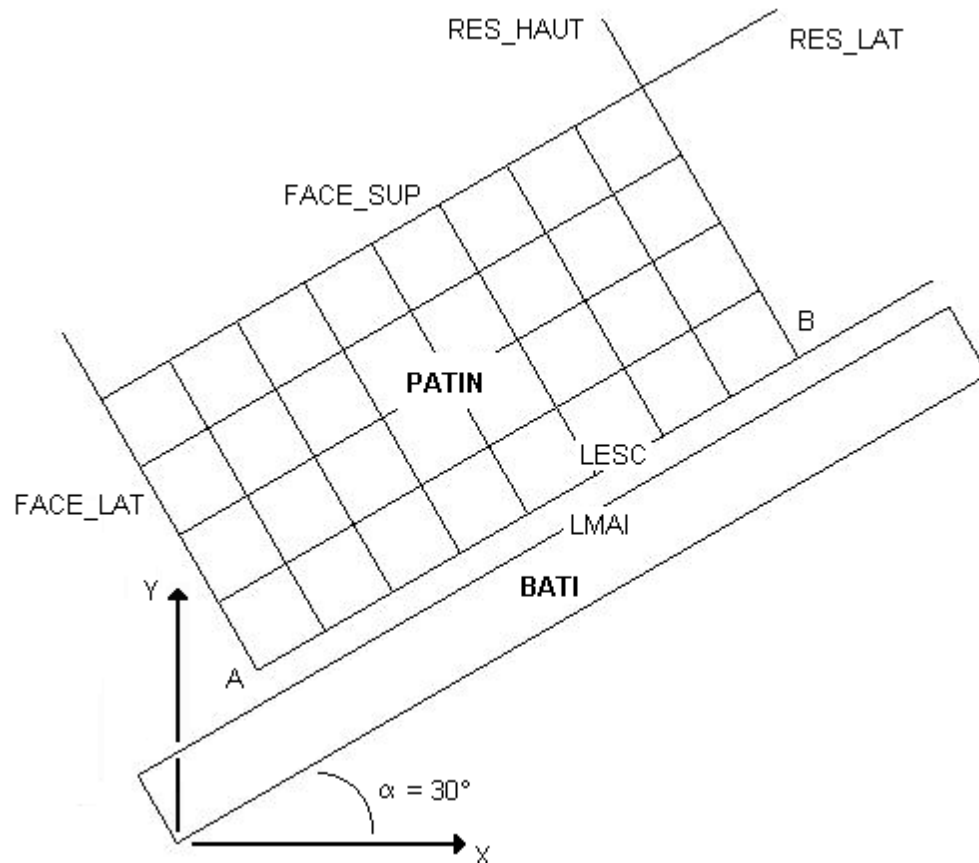
Warning : The translation process used on this website is a "Machine Translation". It may be imprecise and inaccurate in whole or in part and is provided as a convenience.

Normal force of contact	2,0784E+05 N	ANALYTIQUE	RELATIF - 5,00%
tangential Force of contact	-1,2000E+05 N	ANALYTIQUE	RELATIF - 5,00%
DX (not A)	1,000 mm	NON_REGRESSION	RELATIF - 1,00%
DY (not A)	- 1,732 mm	NON_REGRESSION	RELATIF - 1,00%
DX (not B)	1,000 mm	NON_REGRESSION	RELATIF - 1,00%
DY (not B)	- 1,732 mm	NON_REGRESSION	RELATIF - 1,00%
DX (point C)	1,000 mm	NON_REGRESSION	RELATIF - 1,00%
DY (point C)	- 1,732 mm	NON_REGRESSION	RELATIF - 1,00%
DX (not D)	1,000 mm	NON_REGRESSION	RELATIF - 1,00%
DY (not D)	- 1,732 mm	NON_REGRESSION	RELATIF - 1,00%
Loading 2			
Normal force of contact	1,722E+05 N	ANALYTIQUE	RELATIF - 5,00%
tangential Force of contact	- 1,8173E+05 N	ANALYTIQUE	RELATIF - 5,00%
DX (not A)	1,000 mm	NON_REGRESSION	RELATIF - 2,3 0%
DY (not A)	- 1,732 mm	NON_REGRESSION	RELATIF - 1,00%
DX (not B)	1,000 mm	NON_REGRESSION	RELATIF - 1,00%
DY (not B)	- 1,732 mm	NON_REGRESSION	RELATIF - 1,00%
DX (point C)	1,000 mm	NON_REGRESSION	RELATIF - 1,00%
DY (point C)	- 1,732 mm	NON_REGRESSION	RELATIF - 1,00%
DX (not D)	1,000 mm	NON_REGRESSION	RELATIF - 1,00%
DY (not D)	- 1,732 mm	NON_REGRESSION	RELATIF - 1,00%
Loading 3			
Normal force of contact	1,71486E+05 N	ANALYTIQUE	RELATIF - 5,00%
tangential Force of contact	- 1,82977E+05 N	ANALYTIQUE	RELATIF - 5,00%
DX (not A)	8,794 mm	NON_REGRESSION	RELATIF - 1,00%
DY (not A)	2,768 mm	NON_REGRESSION	RELATIF - 1,00%
DX (not B)	8,794 mm	NON_REGRESSION	RELATIF - 1,00%
DY (not B)	2,768 mm	NON_REGRESSION	RELATIF - 1,00%
DX (point C)	8,794 mm	NON_REGRESSION	RELATIF - 1,00%
DY (point C)	2,768 mm	NON_REGRESSION	RELATIF - 1,00%
DX (not D)	8,794 mm	NON_REGRESSION	RELATIF - 1,00%
DY (not D)	2,768 mm	NON_REGRESSION	RELATIF - 1,00%

21 Modelization J

21.1 Characteristic of the modelization

a simulation in flat strains are carried out: a modelization with elements QUAD4 in D_PLA N for meshes of the SHOE and FRAME and D_PLA N_JOINT for joint FISS. One tests the features of contact penalized in compression with friction treated via a constitutive law JOIN_MECA_FROT.



Clearance between the shoe and the frame is defined only for visualization of the contact, it does not influence the results physique (characteristic of modelization of joint). The parameter of regularization of the model east chooses of kind not to influence not (less than 0.01%) the replacement final one of shoe in glissement.

K_N : $K_n = 10^5 \text{ N/mm}^3$ parameter of penalization in compression and sliding

to avoid rigid body motions, the shoe is maintained by springs of low stiffness:

RES_LAT : $k = 2 \text{ N/mm}$
RES_HAUT : $k = 0,005 \text{ N/mm}$

Boundary conditions:

Loose lead of springs: $DX = DY = 0$.
Frame: $DX = DY = 0$.

21.2 Characteristics of the mesh

Warning : The translation process used on this website is a "Machine Translation". It may be imprecise and inaccurate in whole or in part and is provided as a convenience.

Many nodes: 134
Number and types of meshes: 96 QUAD4, 68 SEG2

22 Results of the modelization J

22.1 Values tested

Standard	Identification	Reference	Tolerance
Loading 1			
Normal force of contact	1,200E+04 N	ANALYTIQUE	RELATIF – 1,00%
tangential Force of contact	0 N	ANALYTIQUE	ABSOLU – 5,00%
DX (not A)	1,5E-3 mm	ANALYTIQUE	RELATIF – 1,00%
DY (not A)	– 2.598E-3 mm	ANALYTIQUE	RELATIF – 1,00%
DX (not B)	1,5E-3 mm	ANALYTIQUE	RELATIF – 1,00%
DY (not B)	– 2.598E-3 mm	ANALYTIQUE	RELATIF – 1,00%
Loading 2			
Normal force of contact	1,200E+04 N	ANALYTIQUE	RELATIF – 1,00%
tangential Force of contact	– 3,564E+03 N	ANALYTIQUE	RELATIF – 1,00%
DX (not A)	0.0234 mm	NON_REGRESSION	RELATIF – 1,00%
DY (not A)	0.0122 mm	NON_REGRESSION	RELATIF – 1,00%
DX (not B)	4.032E-03 mm	NON_REGRESSION	RELATIF – 1,00%
DY (not B)	–4.747 mm	NON_REGRESSION	RELATIF – 1,00%
Loading 3			
Normal force of contact	1,200E+04 N	ANALYTIQUE	RELATIF – 1,00%
tangential Force of contact	– 3,624E+03 N	ANALYTIQUE	RELATIF – 1,00%
DX (not A)	2.598 mm	ANALYTIQUE	RELATIF – 1,00%
DY (not A)	1.5 mm	ANALYTIQUE	RELATIF – 1,00%
DX (not B)	2.598 mm	ANALYTIQUE	RELATIF – 1,00%
DY (not B)	1.5 mm	ANALYTIQUE	RELATIF – 1,00%

the analytical values for loading 1 are obtained by means of the fact that the joint is elastic thanks to the parameter of penalization. It is this value which one projects in the reference total.

$$D_{norm} = P_{norm} / K_n = 300 / 10^5 = 3 \cdot 10^{-3} ; DX = D_{norm} \cos(\pi/6) ; DY = D_{norm} \sin(\pi/6)$$

23 Summary of the results

Whatever that is to say the modelization (2D or 3D) and the method of processing of contact-friction, the got results are satisfactory. They are very close to the analytical results.