
SSNV172 – Single-crystal viscoplastic behaviors

Abstract:

This test makes it possible to validate the single-crystal behaviors in a uniaxial situation. The treated geometry is a cube, the stress state and strains is homogeneous. In order to test the constitutive laws as well as possible, independently of the definition of sliding systems, here a system of particular sliding, nonphysical is used, which represents a sliding in only one direction. This makes it possible to compare two of the single-crystal viscoplastic behaviors, (with kinematic hardening defined by a variable of recall) with the macroscopic viscoplastic behavior of Chaboche.

For other behaviors (in particular `KOCKS_RAUCH`) one checks only non regression results.

All these tests are carried out in the modelization A (3D).

The modelization B allows to validate, always by intercomparison with the model of Chaboche, the single-crystal behaviors in 2D (`C_PLAN`).

- Type of kinematic hardening: **MONO_CINE1** whose parameters are:

$$d = 36.68$$

The family of sliding systems is: **UNIAXIAL**

Two computations are carried out: one with implicit local integration, the other with explicit local integration. It is checked that these two computations provide identical results (with the temporal discretization near).

1.2.3 Behavior single-crystal of type 2, comparable to type 1, with system of sliding **UNIAXIAL**

the behavior of the monocystal is defined in such way that one is reduced to the behavior of type 1. The results must thus correspond. The parameters are:

- Type of flow: **MONO_VISC2** whose parameters are:

$$n = 10 \quad k = 40 \text{ MPa} \quad c = 10 \text{ MPa} \quad d = 0, \quad a = 0$$

- isotropic Type of hardening: **MONO_ISOT2** whose parameters are:

$$R_0 = 75.5 \quad b_1 = 19.34 \quad b_2 = 0 \quad Q_1 = 9.77 \text{ MPa} \quad Q_2 = 0$$

- Type of kinematic hardening: **MONO_CINE2** whose parameters are:

$$d = 36.68 \quad M = 0 \quad m = 0 \quad c = 0$$

The family of sliding systems is: **UNIAXIAL**

Two computations are carried out: one with implicit local integration, the other with explicit local integration. It is checked that these two computations of type 1. provide results identical to those of the single-crystal behavior

1.2.4 Behavior single-crystal of type 2, complete test

the parameters of the behavior of the monocystal of the type 2 are all non-zero:

- Type of flow: **MONO_VISC2** whose parameters are:

$$n = 10 \quad k = 40 \text{ MPa} \quad c = 10 \text{ MPa} \quad d = 0.1, \quad a = 0.5$$

- isotropic Type of hardening: **MONO_ISOT2** whose parameters are:

$$R_0 = 75.5 \quad b_1 = 19.34 \quad b_2 = 10 \quad Q_1 = 9.77 \text{ MPa} \quad Q_2 = 10$$

- Type of kinematic hardening: **MONO_CINE2** whose parameters are:

$$d = 36.68 \quad M = 10 \quad m = 0.1 \quad c = 10$$

The family of sliding systems is: **UNIAXIAL**. The tests are of non regression.

1.2.5 Computation with the behavior monocystal of the type 1 and one orthotropic elasticity

the parameters of the orthotropy correspond in fact to the isotropy:

```
ELAS_ORTH=_F ( E_L = 145200.0,
               E_T = 145200.0,
               E_N = 145200.0,
               NU_LT = 0. ,
               NU_LN = 0. ,
               NU_TN = 0. ,
               G_LT = 72600. ,
               G_LN = 72600. ,
               G_TN = 72600. )
```

the results must thus correspond to the computation of reference. Two computations are carried out: one with implicit local integration, the other with explicit integration.

Warning : The translation process used on this website is a "Machine Translation". It may be imprecise and inaccurate in whole or in part and is provided as a convenience.

1.2.6 Computation with the behavior monocrystal of the type 1 and the sliding systems of ZIRCONIUM

Five computations are carried out with this family of sliding systems:

- 1.a computation of non regression with the family defined in the code
- 2.a comparative computation in the first, by providing an array containing the matrix of interaction
- 3.a comparative computation to the precedents, with a polycrystal comprising only one grain,
- 4.a comparative computation with the precedents, by providing five families defined from an array containing sliding systems. The set of these systems corresponds to the Zirconium family. This tests the possibility of defining different coefficients material according to sliding systems considered,
- 5.a computation identical to the precedent, with a polycrystal comprising only one grain.

1.2.7 Behavior Kocks-Rauch: single-crystal, with system of sliding BCC24

the behavior of the monocrystal is defined by flow: `MONO_DD_KR` whose parameters are:

```
K          = 8.62E-5,  
TAUR       = 498. ,  
TAU0       = 132. ,  
GAMMA0    = 1.E6,  
DELTA0    = 0.768,  
BSD       = 2.514E-5,  
GCB       = 31.822,  
KDCS      = 22.9,  
P         = 0.335,  
Q         = 1.12,  
H1        = 0.25,  
H2        = 0.25,  
H3        = 0.25,  
H4        = 0.25
```

Three computations are carried out with this behavior:

- 1) An implicit computation `MONOCRISTAL`
- 2) a computation `MONOCRISTAL` clarifies
- 3) a computation `POLYCRISTAL` clarifies, with only one phase

These three computations must lead to the same results.

1.3 Boundary conditions and loadings

The node is outside the field of $DX = DY = 0$ definition with a right profile of the EXCLU type node: *P4*

The node is outside the field of $DX = DY = DZ = 0$ definition with a right profile of the EXCLU type node: *P8*

Nodes *P2* and *P6* : $DX = 0$

Nodes *P1* *P3*, *P5* and *P7* : either $FX = 25$, or $DX = 0.001$

the loading in imposed force is increasing of $FX = 0$ with $FX = 25 \times 0.755 N$, in an increment, which leads to a uniaxial stress state of $75.5 MPa$ (limit of linearity)

the loading believes then until $FX = 25 \times 0.955 N$ in *n* increments. The computation from reference is obtained with $n = 100$. Single-crystal computations are carried out with $n = 20$.

With regard to behaviors `MONO_VISC2` and `MONO_DD_KR`, the loading is a varying imposed displacement of 0, at initial time, 0.001 at time 2, in *m* increments.

For the implicit resolutions $m=20$, and the explicit resolutions $m=100$.

For the modelization B the loading is a varying imposed displacement of 0, at initial time, 0.001 at time 3, in 20 increments.

2 Reference solution

2.1 Méthode de calcul

In 3D , (modelization A), the first computation (behavior `VISC_CIN1_CHAB`) is used as reference. The values obtained with the last increment are (in any point of the mesh):

Stress	<i>SIXX</i>	-9.55E+01
total Deflection	<i>EPXX</i>	-6.76443E-04
Plastic strain	<i>EPXX</i>	-1.87292E-05

computations with `MONO_ISOT1` or the first computations with `MONO_ISOT2` is validated by comparison with this result or intercomparison.

On the other hand, other computations (behaviors `MONO_VISC2`, `MONO_DD_KR`) do not have a value of reference. The tests are thus of NON-regression. Moreover, five computations corresponding to Zirconium do not have a reference solution but must give only one and even solution.

In 2D , (modelization B), the first computation (behavior `VISC_CIN1_CHAB`) is used as reference. The values obtained with the last increment are (in any point of the mesh, because one imposes a uniform strain):

Stress	<i>SIXX</i>	95.999316
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the second and the third computations (behavior `MONOCRISTAL` with system of sliding `UNIAXIAL`) are validated by comparison with this result.

The third computation uses an explicit integration (`RUNGE_KUTTA`), whereas the second computation uses an implicit integration.

3 Modelization A

3.1 Characteristic of the mesh

Many nodes: 8. Modelization 3D : 1 quadratic volume element: **HEXA8**.
The structure contains only one grain, the stress state and of strains is homogeneous.

3.2 Quantities tested and results

3.2.1 Behavior of type 1: MONO_VISC1 , MONO_ISOT1 , MONO_CINE1

Integration	Identification	Reference	% Tolerance
implicit	ε_{xx} of EPSI_ELGA	-6.764427E-04	0.10
implicit	ε_{xx} of EPSP_ELGA	-1.87292E-05	2.0
Behavior	ε_{xx} clarifies	EPSI_ELGA	-6.764427E-04
0.2	ε_{xx} explicit of	EPSP_ELGA	-1.87292E-05

3.2.2 4.0 of type 2: MONO_VISC2 , MONO_ISOT2 , MONO_CINE2

Comparison between MONO_VISC2 , MONO_ISOT2 , MONO_CINE2 and MONO_VISC1 , MONO_ISOT1 , MONO_CINE1

Integration	Identification	Reference	% Tolerance
implicit	ε_{xx} of EPSI_ELGA	-6.76241E-04	0.10
implicit	ε_{xx} of EPSP_ELGA	-1.85279E-05	0.10
Behavior	ε_{xx} clarifies	EPSI_ELGA	-6.757537E-04
0.10	ε_{xx} explicit of	EPSP_ELGA	-1.804038E-05

3.2.3 0.10 of type 2: MONO_VISC2 , MONO_ISOT2 , Non regression

MONO_CINE2 for MONO_VISC2 , MONO_ISOT2 , MONO_CINE2

Integration	Identification	Reference	% Tolerance
implicit	σ_{xx} of EPSI_ELGA	-95.9311	0.10
implicit	ε_{xx} of EPSP_ELGA	-1.3393175E-03	0.10

3.2.4 Behavior of type 1 with ELAS_ORTH

Comparison between MONO_VISC1 , MONO_ISOT1 , MONO_CINE1 , with ELAS and ELAS_ORTH

Integration	Identification	Reference	% Tolerance
implicit	ε_{xx} of EPSI_ELGA	-6.76241E-04	0.10
Behavior	ε_{xx} clarifies	EPSI_ELGA	-6.75754E-04

3.2.5 0.10 of type 1: MONO_VISC1 , MONO_ISOT1 , MONO_CINE1 for ZIRCONIUM

the First computation: sliding systems stamp interaction (matrix identity h=0) and defined in Code_Aster:

Integrat	Identification	Reference	% Tolerance
Implicit	σ_{xx} of SIEF_ELGA	-212.31	0.1
implicit	ε_{xx} of EPSP_ELGA	-5.3785E-04	0.1
implicit	ν_{92} of VARI_ELGA	5.2868E-04	the 0.1

Second computation: sliding systems defined in Code_Aster, matrix of interaction defined by the user (matrix identity, provided in data in an array). Comparison with the first computation.

Integrat	Identification	Reference	% Tolerance
Implicit	σ_{xx} of SIEF_ELGA	-212.3	0.1
implicit	ε_{xx} of EPSP_ELGA	-5.3785E-04	0.1
implicit	ν_{92} of VARI_ELGA	5.2868E-04	the 0.1

Third computation: sliding systems defined in Code_Aster, matrix of interaction defined by the user (matrix identity, provided in data in an array), and behavior POLYCRYSTAL :

Integrat	Identification	Reference	% Tolerance
Polycrystal	σ_{xx} of SIEF_ELGA	-212.3	0.1
Polycrystal	ε_{xx} of EPSP_ELGA	-5.3785E-04	0.1
Polycrystal	ν_{99} of VARI_ELGA	5.2868E-04	the 0.1

Fourth computation: sliding systems and interaction stamps defined by the user:

Integrat	Identification	Reference	% Tolerance
Implicit	σ_{xx} of SIEF_ELGA	-212.3	0.1
implicit	ε_{xx} of EPSP_ELGA	-5.3785E-04	0.1
implicit	ν_{92} of VARI_ELGA	5.2868E-04	the 0.1

Fifth computation: sliding systems and interaction stamps defined by the user, and behavior POLYCRYSTAL (only one phase, to allow the comparison with preceding computations):

Integrat	Identification	Reference	% Tolerance
Polycrystal	σ_{xx} of SIEF_ELGA	-212.3	0.1
Polycrystal	ε_{xx} of EPSP_ELGA	-5.3785E-04	0.3
Polycrystal	ν_{99} of VARI_ELGA	5.2868E-04	0.8

3.2.6 Behavior: MONO_DD_KR

Integrat	Identification	Reference	% Tolerance
implicit	σ_{xx} of SIEF_ELGA	-324.37	0.40
implicit	ε_{xx} of EPSP_ELGA	-8.1822E-04	0.20
clarifies	σ_{xx} SIEF_ELGA	-324.37	0.40
explicit	ε_{xx} of EPSP_ELGA	-8.1822E-04	0.05
Polycrystal	σ_{xx} of SIEF_ELGA	-324.37	0.40
Polycrystal	ε_{xx} of EPSP_ELGA	-8.1822E-04	0.05

4 Modelization B

4.1 Characteristic of the mesh

Many nodes: 4.
1 mesh QUAD4.
Modelization C_PLAN (by method DEBORST).

4.2 Quantities tested and results

the Second computation (implicit, MONO_VISC1, MONO_ISOT1, MONO_CINE1)

Identification	Reference	% Tolerance
σ_{xx} of SIEF_ELGA	-95.9993	the 0.10

Third computation (clarifies, MONO_VISC1, MONO_ISOT1, MONO_CINE1)

Identification	Reference	% Tolerance
σ_{xx} of SIEF_ELGA	-95.9993	0.10

5 Summary of the results

the got results are in concord with the reference solution. The noted difference (3,6% to the maximum) comes from the different numerical diagrams, sensitive to the temporal discretization.