

## SSNV103 - Traction test shears models of Summarized

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### Rousselier:

It is about a nonlinear quasi-static problem in structural mechanics.

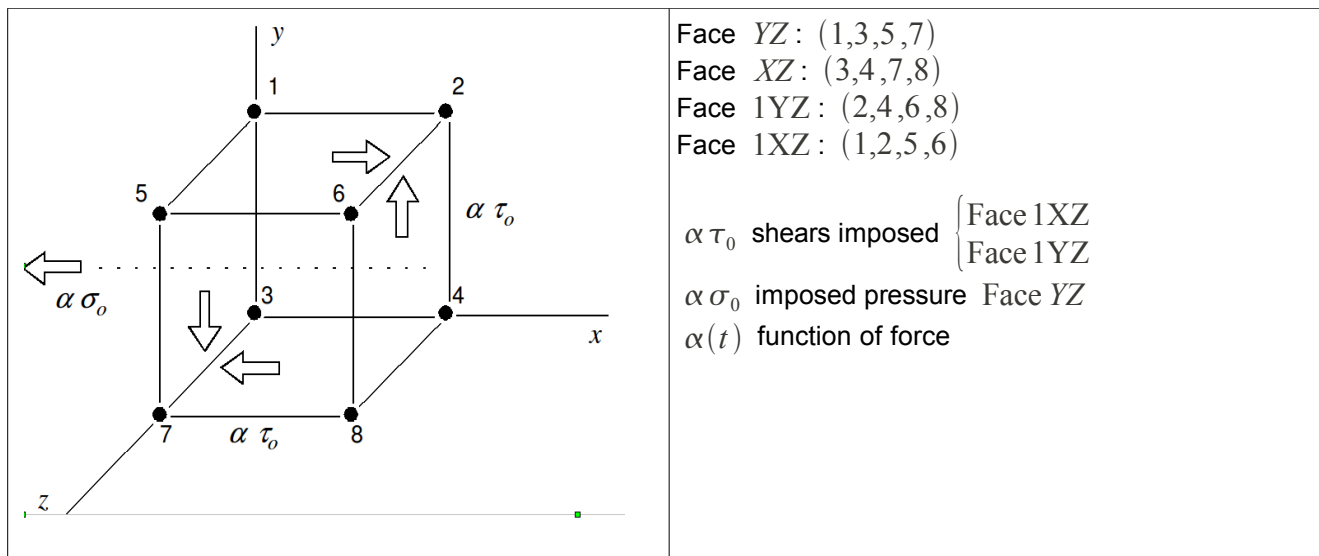
One analyzes the response of a volume element with a loading in tension-shears, carried out in such way that imposes a state of uniform stress-strain.

The case test understands 1 modelization: in 3D .

It G validates the numerical integration of the elastoplastic model of behavior with damage of. Rousselier.

## 1 Problem of reference

### 1.1 Geometry



### 1.2 Material properties

isotropic elasticity:  $E = 206\,400.\text{MPa}$   $\nu = 0.3$

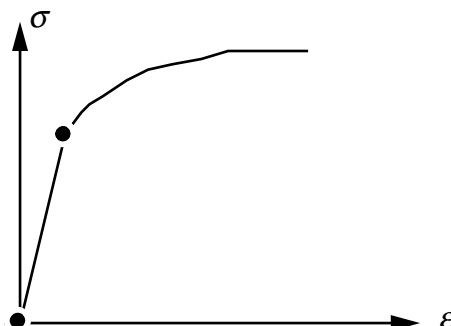
plasticity:  
(coefficients of the model of  
Rousselier)  $D = 2.$   
 $f_0 = 5.10^{-4}$   
 $\sigma_1 = 490.\text{MPa}$

rational curve of tension entered point by point with:

$$R(p) = r_i + (r_0 - r_i) e^{-bp}$$

with  $p$  : cumulated plastic strain

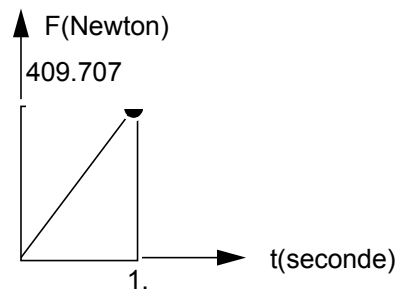
and  $r_i = 1500 \text{ MPa}$   
 $r_0 = 520.\text{MPa}$   
 $b = 2.4$





## 1.3 Boundary conditions and loadings

N04	$dx = dy = 0$	Face YZ :	$F_X = F_Y = -F(t)$
N08	$dx = dy = dz = 0$	Face XZ :	$F_X = -F(t)$
N02, N06	$dx = 0$	Face 1YZ :	$F_Y = F(t)$
		Face 1XZ :	$F_X = F(t)$



## 1.4 Forced

Initial conditions and null strains with  $t=0$ .

## 2 Reference solution

### 2.1 Method of calculating used for the reference solution

The model 3D of velocity is written:

$$\begin{cases} \dot{\sigma} - \dot{p} \Lambda \varepsilon_e - \rho \Lambda \dot{\varepsilon}_e = 0 & (\Lambda \text{ tenseur élasticité isotrope linéaire}) \\ \dot{\beta} - \dot{p} D \exp\left(\frac{\sigma_H}{\sigma_1 \rho}\right) = 0 \\ \dot{\varepsilon} - \dot{\varepsilon}_e - \rho \dot{p} \frac{\partial f}{\partial \sigma} = 0 \\ \dot{f} = 0 \end{cases}$$

what, in the case of a loading of imposed tension-shears  $\left( \sigma(t) = \alpha(t) \begin{bmatrix} \sigma_0 & \tau_0 & 0 \\ \tau_0 & 0 & 0 \\ 0 & 0 & 0 \end{bmatrix} \right)$  results

in integrating a system of 6 ordinary differential equations in  $y = (\varepsilon, \gamma, \varepsilon_e, \gamma_e, \beta, p)$  form  $A(y, t) \dot{y} = G(y, t)$ .

$$(S) \begin{cases} \dot{\alpha} \sigma_0 + \rho^2 F_o e^\beta E \varepsilon_e \dot{\beta} - \rho E \dot{\varepsilon}_e = 0 \\ \dot{\alpha} \tau_0 + \rho^2 F_o e^\beta 2\mu \gamma_e \dot{\beta} - 2\rho \mu \dot{\gamma}_e = 0 \\ \dot{\varepsilon} - \frac{\sigma_0}{\sigma_{eq\ o}} \rho \dot{p} - \dot{\varepsilon}_e = 0 \\ \dot{\gamma} - \frac{3\tau_0}{2\sigma_{eq\ o}} \rho \dot{p} - \dot{\gamma}_e = 0 \\ \dot{\beta} - \dot{p} D \exp\left(\frac{\sigma_H}{\sigma_1 \rho}\right) = 0 \\ \dot{\alpha} \sigma_0 \left[ \frac{\sigma_0}{\rho \sigma_{eq\ o}} + \frac{1}{3} D F_o e^\beta \exp\left(\frac{\sigma_H}{\sigma_1 \rho}\right) \right] + 3 \dot{\alpha} \frac{\tau_0^2}{\rho \sigma_{eq\ o}} - \frac{\partial R}{\partial p} \dot{p} \\ + \left[ \sigma_{eq\ o} F_o e^\beta + D \sigma_1 \rho F_o e^\beta \exp\left(\frac{\sigma_H}{\sigma_1 \rho}\right) \left( 1 - \rho F_o e^\beta \left( 1 - \frac{\sigma_H}{\sigma_1 \rho} \right) \right) \right] \dot{\beta} = 0 \end{cases}$$

with  $t=0$  :

$$f = 0 \quad \rho(0) = 1, \quad \beta(0) = 0$$

from where:

$$\alpha(0) \sigma_{eq0} - R(0) + D \sigma_1 F_o \exp\left(\frac{\alpha(0) \sigma_0}{3 \sigma_1}\right)$$

who is solved by a method of NEWTON for  $\alpha(0)$  :

$$\begin{cases} \varepsilon(0) &= \frac{1}{E}\alpha(0)\sigma_0 &= \varepsilon_e(0) \\ \gamma(0) &= \frac{1}{2\mu}\alpha(0)\tau_0 &= \gamma_e(0) \\ p(0) &= &0 \end{cases}$$

## 2.2 Results of reference

One imposes  $\alpha(t)=\alpha(0)+t$  with  $\sigma_0=\tau_0=150 \text{ MPa}$ .

One obtains  $\alpha(0)=1.73138$  and  $\alpha(1)=2.73138$ .

The system  $(S)$  is then solved numerically by a "Backward difference formulated" using scientific library NAG on CRAY. Result of reference =  $(\varepsilon, \gamma, \beta, \rho)$  to the nodes to  $t=1$ .

## 2.3 Uncertainty on the solution

Uncertainty related to library NAG.

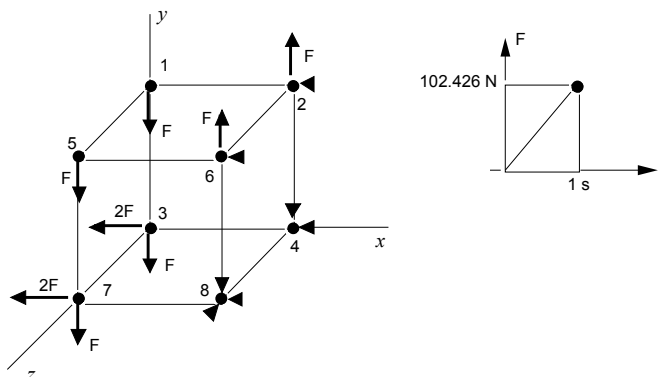
## 2.4 Bibliographical references

- 1) User's manual library NAG on CRAY.

### 3 Modelization A

#### 3.1 Characteristic of the modelization

Modelization 3D



#### 3.2 Characteristic of the mesh

The mesh contains 1 element of type HEXA8.

#### 3.3 Quantities tested and results of the modelization A

Identification	Reference	Test	Tolerance
$\varepsilon$ on NO1 to $t=1s$	0,07830	ANALYTIQUE	0,11%
$\gamma$ out of NO1 to $t=1s$	0,11700	ANALYTIQUE	0,20%
$p$ out of NO1 to $t=1s$	0,15260	ANALYTIQUE	0,10%
$\sigma_{11}$ out of NO1 to $t=1s$	409.70700	ANALYTIQUE	0,05%

One also tests the parameters of the data structure results:

Identification	Reference	Test	Tolerance
INST for NUME ORDRE=8	1	ANALYTIQUE	0%
ITER_GLOB for NUME ORDRE=8	4	NON_REGRESSION	0%

#### 3.4 Remarks

One could expect a better correlation, but it should be stressed that library NAG uses the function  $R(p)$  in algebraic form, whereas Code\_Aster uses it in the form of a point by point given curve.

Moreover, it seems that the integration of the rate of the function threshold poses problems with NAG, whatever the accuracy required in addition (the value of the threshold  $f$  being appreciably different from 0 at the end of the integration). However, one can note the constancy of this correlation throughout integration ( $t \in [0,1]$ ).

## 4 Summary of the results

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the values of `Code_Aster` are in concord with the values of reference.