

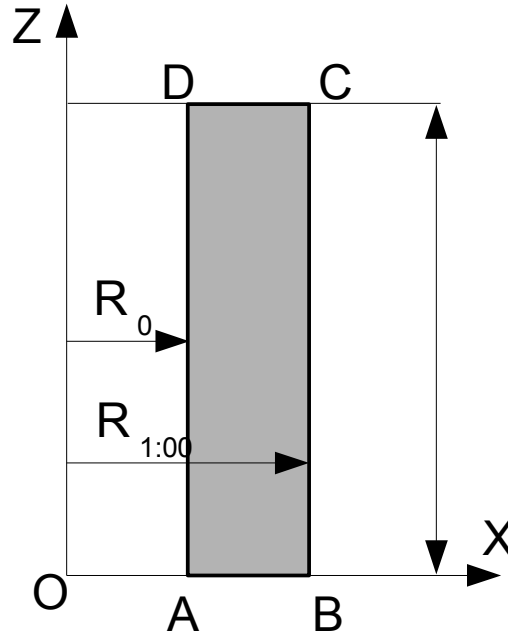
SSNA107 – Hollow roll in nonlinear viscoelasticity

Summarized:

This benchmark makes it possible to validate the model of LEMAITRE established in Code_Aster in the case of viscoelastic behavior nonlinear. The found results are compared with an analytical solution.

1 Problem of reference

1.1 Geometry



Geometry of the cylinder (m) :

$$\begin{aligned} R_0 &= 1 \\ R_1 &= 1.02 \\ H &= 1 \end{aligned}$$

1.2 Properties of the Elastic

material

- Young Modulus: $E = 1.0 \times 10^6 Pa$
- Poisson's ratio: $\nu = 0.3$

LEMAITRE

$$g(\sigma, \lambda, T) = \left(\frac{1}{K} \frac{\sigma}{\left(\frac{1}{\lambda^m} \right)} \right)^n \quad \text{with } n=2; \quad \frac{1}{K}=1; \quad \frac{1}{m}=0$$

CIN1_CHAB

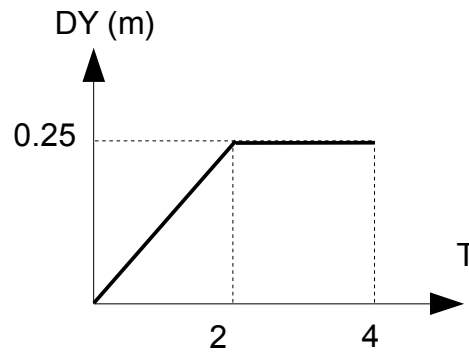
$$\begin{aligned} R_0 &= 0. \\ R_1 &= 0. \\ B &= 0. \\ C_1 &= 0. \\ K &= 0. \\ W &= 0. \\ G_0 &= 0. \end{aligned}$$

$A_I = 0.$

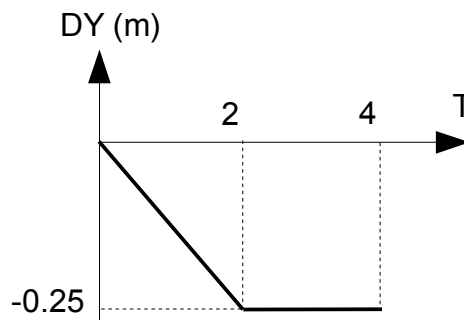
1.3 Boundary conditions and loadings

imposed Displacement (m):

Dimensioned CD



With dimensions AB



2 Reference solution

2.1 Méthode de calcul used for the reference solutions

the group of this demonstration can be read with more details in the document [1]

the stress tensor is written:

$$\sigma = \begin{pmatrix} 0 & 0 & 0 \\ 0 & 0 & 0 \\ 0 & 0 & \sigma_z \end{pmatrix}$$

Because of the loading, one a:

$$\begin{cases} \varepsilon_z - \varepsilon_{vz} = \frac{\sigma_z}{E} \\ \varepsilon_\theta - \varepsilon_{v\theta} = -\frac{\nu}{E} \sigma_z \quad \text{and} \quad \dot{\varepsilon}_v = \frac{3}{2} g(\sigma^*) \frac{\sigma^D}{\sigma^*} \\ \varepsilon_r - \varepsilon_{vr} = -\frac{\nu}{E} \sigma_z \end{cases}$$

thus

$$\begin{cases} \dot{\varepsilon}_{vz} = g(\sigma_z) \\ \dot{\varepsilon}_{v\theta} = -\frac{1}{2} g(\sigma_z) \\ \dot{\varepsilon}_{vr} = -\frac{1}{2} g(\sigma_z) \end{cases}$$

If $t \leq t_0$, one has $\varepsilon_z = \frac{\varepsilon_0}{t_0} t$,

That is to say $a = \sqrt{\frac{\varepsilon_0}{t_0}}$

One obtains $\varepsilon_z = a^2 t$

While replacing, one finds:

$$\dot{\varepsilon}_{vz} = g((a^2 t - \varepsilon_{vz}) E)$$

One poses $E=1$ and $z = a^2 t - \varepsilon_{vz}$, one obtains: $\dot{z} = a^2 - z^2$

While integrating with $z(0)=0$ one obtains:

$$z = a \tanh(at)$$

For $t \leq t_0$

$$\left\{ \begin{array}{l} \sigma_r = \sigma_\theta = 0 \\ \sigma_z = a \tanh(at) \\ \varepsilon_r = \varepsilon_\theta = a \left[\left(\frac{1}{2} - \nu \right) \tanh(at) - \frac{1}{2} at \right] \\ \varepsilon_z = a^2 t \\ w = ar \left[\left(\frac{1}{2} - \nu \right) \tanh(at) - \frac{1}{2} at \right] \end{array} \right.$$

If $t \geq t_0$

$$\begin{aligned} \varepsilon_z &= a^2 t_0 \\ \varepsilon_{vz} &= g(a^2 t_0 - \varepsilon_{vz}) = (a^2 t_0 - \varepsilon_{vz})^2 \end{aligned}$$

What gives while integrating:

$$\varepsilon_{vz} = a^2 t_0 - \frac{1}{\frac{1}{a \tanh(at_0)} + t - t_0}$$

There is thus with final

$$\left\{ \begin{array}{l} \sigma_r = \sigma_\theta = 0 \\ \sigma_z = \frac{1}{\frac{1}{a \tanh(at_0)} + t - t_0} \\ \varepsilon_r = \varepsilon_\theta = \left(\frac{1}{2} - \nu \right) \frac{1}{\frac{1}{a \tanh(at_0)} + t - t_0} - \frac{1}{2} a^2 t_0 \\ \varepsilon_z = a^2 t_0 \\ w = r \left[\left(\frac{1}{2} - \nu \right) \frac{1}{\frac{1}{a \tanh(at_0)} + t - t_0} - \frac{1}{2} a^2 t_0 \right] \end{array} \right.$$

2.2 the Forced reference Variables

- DX Déplacement au B

•node $SIXX$, $SIYY$ and $SIZZ$ with the node B

2.3 Results of reference

Quantity	Not	Urgent	Reference
DX	B	4	-0.2109
$SIXX$	B	4	0.
$SIYY$	B	4	0.2616
$SIZZ$	B	4	0.

2.4 Uncertainty on the analytical

solution Solution

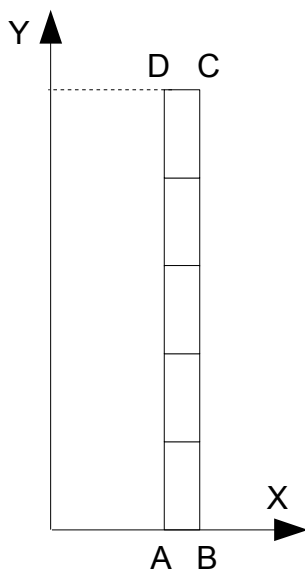
2.5 bibliographical References

- [1] pH. BONNIERES, Mr. ZIDI: Introduction of viscoplasticity into the modulus of thermomechanics of Cyrano3 : Principle, description and validation, Note HI-71/8334.

3 Modelization A

3.1 Characteristic of the modelization A

viscoelastic Modelization
AXIS Behavior model of LEMAITRE



3.2 Characteristic of the mesh

Many nodes 12
Number of meshes 17 Is:
SEG2 12
QUAD4 5

Nodes groups:
A, B, C, D

Mesh groups :
MAIL : surface *ABCD*
DAB : segment *AB*
DBC : segment *BC*
DCD : segment *CD*
DDA : segment *DA*

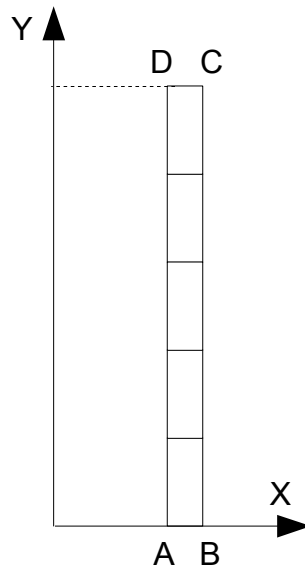
3.3 Quantities tested and Quantity

results	Not	Urgent	Reference	Aster	Variation %
<i>DX</i>	<i>B</i>	4	-0.2109	-0.2109	0,001%
<i>SIXX</i>	<i>B</i>	4	0.	4,82E-9	-
<i>SIYY</i>	<i>B</i>	4	0.2616	0.2616	0,002%
<i>SIZZ</i>	<i>B</i>	4	0.	4,82E-9	-

4 Modelization B

4.1 Characteristic of the modelization B

viscoelastic Modelization
AXIS Behavior model of VISC_CIN1_CHAB



4.2 Characteristic of the mesh

Many nodes 12
Number of meshes 17 Is:
SEG2 12
QUAD4 5

Nodes groups:
A, B, C, D

Mesh groups :

- MAIL* : surface *ABCD*
- DAB* : segment *AB*
- DBC* : segment *BC*
- DCD* : segment *CD*
- DDA* : segment *DA*

4.3 Quantities tested and Quantity

results	Not	Urgent	Reference	Aster	Variation %
<i>DX</i>	<i>B</i>	4	-0.2109	-0.2109	0,026%
<i>SIXX</i>	<i>B</i>	4	0.	1,55E-10	-
<i>SIYY</i>	<i>B</i>	4	0.2616	0.2616	0,130%
<i>SIZZ</i>	<i>B</i>	4	0.	1,55E-10	-

5 Summary of the results

the results calculated by Code_Aster are in excellent agreement with the analytical solutions.