

## SSNA106 - Hollow roll subjected to a Summarized behavior

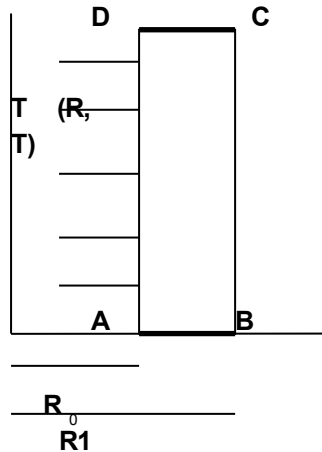
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### thermoviscoelastic:

This benchmark makes it possible to validate the model of LEMAITRE established in *Code\_Aster* in the linear case of behavior thermoviscoelastic. The found results are compared with an analytical solution.

## 1 Problem of reference

### 1.1 Geometry



$$\begin{aligned} R_0 &= 1 \text{ m} \\ R_1 &= 2 \text{ m} \end{aligned}$$

### 1.2 Properties of the materials

Modulus Young:  $E = 1 \text{ MPa}$

Poisson's ratio:  $\nu = 0.3$

Coefficient of thermal expansion:  $\alpha = 0.7$

Model of LEMAITRE:

$$g(\sigma, \lambda, T) = \left( \frac{1}{K} \frac{\sigma}{\lambda^{\frac{1}{m}}} \right)^n \quad \text{with} \quad \frac{1}{K} = 1, \quad \frac{1}{m} = 0, \quad n = 1$$

### 1.3 Boundary conditions and loading

**Boundary conditions:**

The cylinder is blocked in  $DY$  on the sides  $[AB]$  and  $[CD]$ .

**Loading:**

The cylinder is subjected to a field of temperature  $T(r, t) = t r^2$

## 2 Reference solutions

### 2.1 Method of calculating used for the reference solutions

the group of this demonstration can be read with more details in the document [bib1].

In the case of a linear viscoelastic isotropic material, one can describe the behavior in the course of time using two functions  $I(t)$  and  $K(t)$  so that the strains and the forced can be written:

$$\varepsilon(t) = (I + K) * \frac{d\sigma(t)}{d\tau} - K * \frac{d(\text{Tr}(\sigma(t)))}{d\tau} \mathbf{I}_3 + \alpha T(r, t) \mathbf{I}_3$$

where  $\mathbf{I}_3$  indicates the matrix identity of row 3

and  $*$  the product of convolution:  $(f * g)(t) = \int_0^t f(t - \tau)g(\tau)d\tau$

The thermo-elastic problem are equivalent, via the transform of Laplace is:

$$\begin{cases} \varepsilon^+ = (I^+ + K^+) \sigma^+ - K^+ \text{Tr}(\sigma^+) \mathbf{I}_3 + \frac{\alpha r^2}{p} \mathbf{I}_3 \\ \sigma_r^+{}' = \frac{d\sigma_r^+}{dr} = \frac{1}{r} (\sigma_\theta^+ - \sigma_r^+) \\ \varepsilon_z^+ = 0 \\ (r \varepsilon_\theta^+) = \varepsilon_r^+ \end{cases}$$

By eliminating the sign "+":

$$\begin{cases} \sigma_r^+{}' + \frac{1}{r} (\sigma_r - \sigma_\theta) = 0 \\ (I + K) \sigma_z - K (\sigma_r + \sigma_\theta + \sigma_z) + \frac{\alpha r^2}{p} = 0 \\ \left[ r \left( (I + K) \sigma_\theta - K (\sigma_r + \sigma_\theta + \sigma_z) + \frac{\alpha r^2}{p} \right) \right] = (I + K) \sigma_r - K (\sigma_r + \sigma_\theta + \sigma_z) + \frac{\alpha r^2}{p} \end{cases}$$

maybe,

$$\begin{cases} \sigma_r^+{}' + \frac{1}{r} (\sigma_r - \sigma_\theta) = 0 \\ \sigma_z = \frac{K}{I} (\sigma_r + \sigma_\theta) - \frac{\alpha r^2}{pI} \\ \left[ r \left( (I + K) \sigma_\theta - \frac{(I + K)K}{I} (\sigma_r + \sigma_\theta) + \frac{\alpha r^2}{p} \right) \right] = (I + K) \sigma_r - \frac{(I + K)K}{I} (\sigma_r + \sigma_\theta) + \frac{(I + K) \alpha r^2}{I p} \end{cases}$$

$$(I + K)\sigma_\theta + r \left( (I + K)\sigma_\theta - \frac{(I + K)K}{I}(\sigma_r + \sigma_\theta) + \frac{(I + K)}{I} \frac{\alpha r^2}{p} \right) = (I + K)\sigma_r$$

According to the balance equation, one has  $\sigma_\theta = r\sigma_r' + \sigma_r$ , one obtains:

$$(I + K)\sigma_r' + r \left( (I + K)(r\sigma_r' + \sigma_r) - \frac{(I + K)K}{I}(2\sigma_r + r\sigma_r') + \frac{(I + K)}{I} \frac{\alpha r^2}{p} \right) = 0$$

$$\left[ (2\sigma_r + r\sigma_r') + \frac{\alpha r^2}{p(I - K)} \right] = 0,$$

$$2\sigma_r + r\sigma_r' = A + \frac{\alpha r^2}{p(K - I)} \text{ which while integrating compared to R gives:}$$

$$\sigma_r = \frac{A}{2} + \frac{B}{r^2} + \frac{\alpha r^2}{4p(K - I)},$$

the boundary conditions  $\sigma_r(r_0) = \sigma_r(r_1) = 0$  give:

$$A = -\frac{\alpha}{2p(K - I)}(r_0^2 + r_1^2)$$

$$B = \frac{\alpha r_0^2 r_1^2}{4p(K - I)}$$

One thus has by taking again the initial notations:

$$\begin{cases} \sigma_r^+ = \frac{\alpha}{4p(I^+ - K^+)}(r_0^2 + r_1^2 - r^2 - \frac{r_0^2 r_1^2}{r^2}) \\ \sigma_\theta^+ = \frac{\alpha}{4p(I^+ - K^+)}(r_0^2 + r_1^2 - 3r^2 + \frac{r_0^2 r_1^2}{r^2}) \\ \sigma_z^+ = \frac{\alpha}{p(I^+ - K^+)} \left( \frac{K^+}{I^+} \frac{(r_0^2 + r_1^2)}{2} - r^2 \right) \end{cases}$$

Maybe, by taking the opposite transform,

$$\sigma = \begin{pmatrix} \frac{\alpha}{2k}(1 - e^{-bt}) \left( r_0^2 + r_1^2 - r^2 - \frac{r_0^2 r_1^2}{r^2} \right) & 0 & 0 \\ 0 & \frac{\alpha}{2k}(1 - e^{-bt}) \left( r_0^2 + r_1^2 - 3r^2 + \frac{r_0^2 r_1^2}{r^2} \right) & 0 \\ 0 & 0 & \frac{\alpha}{k} \left[ (1 - e^{-bt})(r_0^2 + r_1^2 - 2r^2) + \frac{r_0^2 + r_1^2}{r^2} (1 - e^{-Ekt}) \right] \end{pmatrix}$$

One from of deduced  $\varepsilon_V$  and  $w$  :

$$w(r, t) = \frac{1 - 2\nu}{Ek} \alpha r \left[ (1 - e^{-bt}) \left[ r_0^2 + r_1^2 - \frac{r_0^2 r_1^2}{r^2} \right] + (1 - e^{-Ekt}) \left[ \frac{-(r_0^2 + r_1^2)}{4} \right] + \frac{3Ekt}{4(1 - 2\nu)} \left[ \frac{r_0^2 r_1^2}{r^2} + r^2 \right] \right]$$

## 2.2 Results of reference

Displacement  $DX$  on the node  $B$

## 2.3 Uncertainty on the solution

0% : analytical solution

## 2.4 bibliographical References

pH. BONNIERES, two analytical solutions of axisymmetric problems in linear viscoelasticity and with unilateral contact, Note HI-71/8301

## 3 Modelization A

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### 3.1 Characteristic of the modelization

the problem is modelled in axisymetry

### 3.2 Characteristics of the mesh

120 meshes QUAD4

### 3.3 Quantities tested and results

Identification	Times	Reference	Tolerance %
$DX(B)$	0.24	1.110	0.1%

## 4 Summary of the results

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the results calculated by *Code\_Aster* are in agreement with the analytical solutions but very strongly depend on the refinement of the mesh.