

SDND103 - Column subjected to an axial dynamic stress

Abstract

It acts to calculate the response of a column subjected to an unspecified seismic loading. The column is modelled by an undamped spring-mass system, its connection with the soil by a non-linearity of type force - displacement.

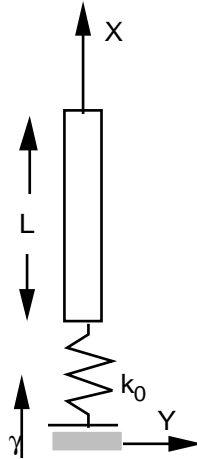
One tests the discrete element in traction and compression, the computation of the eigen modes and the computation of the transient response by modal recombination with taking into account of a non-linearity of type force-displacement. The initial velocity is taken non-zero and the loading is of standard acceleration imposed on the ground.

The got results are in very good agreement with the results of reference which are analytical results.

1 Problem of reference

1.1 Geometry

the system consists of a column resting on the soil and subjected to a seismic request. It is modelled by a mass, its connection with the soil by a spring k_0 whose behavior model translates a non-linearity of type force-displacement.



Characteristics of the column:

length: $L=2 \text{ m}$;
section: $S=0,3 \text{ m}^2$.

1.2 Properties of the materials

Masses column: $m=450 \text{ kg}$.

Stiffness of the come out from connection: $k_0=10^5 \text{ N/m}$.

1.3 Boundary conditions and loadings

Boundary conditions

only authorized displacements are the translations according to the axis X : $dy=dz=0$.

The corrective force F_c due to nonthe linearity of the soil is defined by the following relation:

$$F_c(x) = \frac{f(x_{seuil})}{x_{seuil}} - f(x) \text{ with, if } x > x_{seuil}, f(x) = k_0 \left[1 - \frac{|x|}{x_0} \right] x$$

One takes $x_{seuil}=10^{-6} \text{ m}$, $k_0=10^5 \text{ N/m}$ and $x_0=0,1 \text{ m}$.

One thus imposes under key word `RELA_EFFO_DEPL` of operator `DYNA_VIBRA` the function:

$$F_c(x) = \frac{k_0}{x_0} x. [|x| - x_{seuil}]$$

Loading

the soil is subjected to an acceleration $\gamma(t)$ in the direction x , is built so that the displacement of the spring-mass system is sinusoidal $x = a \cdot \sin(\omega t)$ with $a=0,01$ and $\omega = \pi/4$.

1.4 Initial conditions

In an initial state, the system is released of its equilibrium position with a velocity v_0 : with $t=0$
 $dx(0)=0$ $v_0 = dx/dt(0) = a \cdot \omega$.

2 Reference solution

2.1 Method of calculating used for the reference solution

This test is developed in detail in the reference [bib1].

The fundamental equation of the dynamics, moving relative motion of the spring-mass system compared to the soil is written: $\ddot{x} + \frac{k(x)}{m} x = \gamma(t)$.

For a displacement of the form $x = a \sin(\omega t)$ and $\ddot{x} = -a \omega^2 \sin(\omega t)$, one obtains from the equation of motion the shape of the accelerogram:

$$\gamma(t) = a \sin(\omega t) \left[-\omega^2 + \frac{k_0}{m} \left(1 - \frac{|a \sin(\omega t)|}{x_0} \right) \right]$$

The fundamental frequency f_0 of the undamped oscillator is worth $f_0 = \frac{1}{2\pi} \sqrt{\frac{k_0}{m}}$.

2.2 Results of reference

fundamental Frequency f_0 of the undamped oscillator.
Displacements relating to times 2,6,10,14 and 18 seconds.

2.3 Uncertainty on the solution

No if one calculates the integral of Duhamel analytically [bib2].

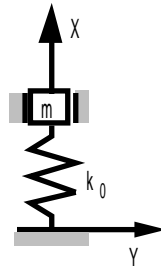
2.4 Bibliographical references

- 1.P. LALUQUE, P. LABBE, S. PETETIN and A. TIXIER: Seismic response of a building engine PWR1300 by taking account of separation enters the foundation and the soil. Note SEPTEN TA83.06 (May 1984).
- 2.J.S. PRZEMIENIECKI: Theory of matrix structural analysis. New York, Mac Graw-Hill, 1968, p. 351-357.

3 Modelization A

3.1 Characteristic of the modelization

the spring-mass system is modelled by a discrete element DIS_T.



Numerical data:

for the spring-mass system: $m = 450 \text{ kg}$
for the soil: $k_0 = 10^5 \text{ N/m}$
for non-linearity: $x_0 = 0,1 \text{ m}$; $a = 0,01$ and $\omega = \pi/4$.

Temporal integration is carried out with the algorithm of Eulerian or the algorithm of Devogelaere and time step of 0,02 second. Computations are filed all time step.

One considers a null ξ_i reduced damping for all the calculated modes.

3.2 Characteristics of the mesh

The mesh consists of a node and a mesh of the type POI1.

3.3 Quantities tested and results

One checks the eigenfrequency of the oscillator as well as displacements relative of the node *NOI* to various times (for the algorithm of integration EULER).

Frequency (Hz)	Reference
	2,37254

relative Displacement of the node *NOI* with the algorithm of numerical integration of Eulerian:

Time (S)	Reference
2	0,01
6	- 0,01
10	0,01
14	- 0,01
18	0,01

relative Displacement of the node *NOI* with the algorithm of numerical integration of Devogelaere:

Time (S)	Reference
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2	0,01
6	- 0,01
10	0,01
14	- 0,01
18	0,01

4 Summary of the results

One notes very a good agreement with the analytical solution (error lower than 0,01%).