

SDLL401 - Inclined straight beam with 20°, subjected to sinusoidal forces

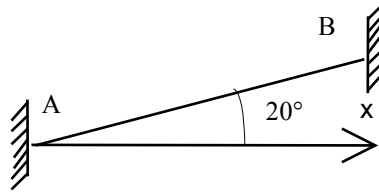
Summarized:

This test is resulting from the validation independent of version 4 of the models of beams.

It makes it possible to check the internal forces on an inclined beam, for sinusoidal loadings according to time (a modelization with elements `POU_D_T`, straight beam of Timoshenko).

1 Problem of reference

1.1 Geometry



Appears 1.1-1.1-a1.1-a

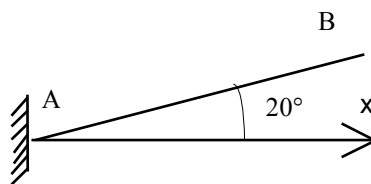


Figure 1.1-1.1-b1.1-b

Straight beam length 1 m .
slope 20° compared to x (trigonometrical meaning).

Characteristics of the section:

$$S = \pi \times 0.01^2 \text{ m}^2$$

1.2 Properties of the materials

Modulus Young	$E = 2.10^{11} \text{ Pa}$
Poisson's ratio	$\nu = 0,3$
Density	$\rho = 7800 \text{ kg/m}^3$

1.3 Boundary conditions and loading

Boundary condition:

- For the distributed loading [fig 1.1-1]
Nodes A and B clamped: $DX, DY, DZ, DRX, DRY, DRZ$ blocked
- For the specific loading [fig 1.1-2]
clamped A Node: $DX, DY, DZ, DRX, DRY, DRZ$ blocked

Loadings:

- $f(t) = 1000 \times \cos(t)$ according to the direction AB
either distributed or applied at the end B
- $M_T(t) = 1000 \times \cos(t)$ applied at the Reference solutions B

2 end

2.1 Method of calculating used for the reference solutions

2.1.1 Distributed loading of traction and compression

a straight beam length L working only in traction and compression is subjected to a following constant distributed loading x but varying in a sinusoidal way according to time. It is embedded at its two ends.

$$\begin{cases} \rho S \frac{\partial^2 u}{\partial t^2} - ES \frac{\partial^2 u}{\partial x^2} = f(t) \\ u(0) = 0, u(L) = 0 \end{cases}$$

To solve, one applies to the equation the transform of Fourier in time:

$$\frac{\partial^2 \hat{u}}{\partial x^2} = -\frac{\rho}{E} 4\pi^2 \omega^2 \hat{u} + \frac{1}{ES} \hat{f}(\omega)$$

\hat{u} : transform of Fourier of u
 \hat{f} : transform of Fourier of f .

Thus, we have for $f(t) = F \cos(2\pi \omega_0 t)$:

$$u(x,t) = \frac{a^2 F}{ES 4\pi^2 \omega_0^2} \left\{ \left[\cos\left(\frac{2\pi\omega_0}{a} L\right) - 1 \right] \frac{\sin\left(\frac{2\pi\omega_0}{a} x\right)}{\sin\left(\frac{2\pi\omega_0}{a} L\right)} - \left[\cos\left(\frac{2\pi\omega_0}{a} x\right) - 1 \right] \right\} \cos(2\pi \omega_0 t).$$

with: $a^2 = \frac{E}{\rho}$.

The use of the constitutive law gives us the tractive effort compression:

$$N(x,t) = \frac{a F}{2\pi \omega_0} \left\{ \left[1 - \cos\left(\frac{2\pi\omega_0}{a} L\right) \right] \frac{\cos\left(\frac{2\pi\omega_0}{a} x\right)}{\sin\left(\frac{2\pi\omega_0}{a} L\right)} + \sin\left(\frac{2\pi\omega_0}{a} x\right) \right\} \cos 2\pi \omega_0 t.$$

2.1.2 Specific loadings

a cantilever beam length L working only in tension compression (or torsion) is subjected to a sinusoidal force in time, (or a moment) applied at its loose lead.

2.1.2.1 Tension

$$\begin{cases} \rho S \frac{\partial^2 u}{\partial t^2} - ES \frac{\partial^2 u}{\partial x^2} = 0 \\ u(0) = 0, \quad \frac{\partial u}{\partial x}(L) = \frac{1}{ES} f(t). \end{cases}$$

the technique of resolution is equivalent to that of the paragraph [§ 2.1.1.1].

For $f(t) = F \cos(2\pi\omega_0 t)$, we have:

$$u(x, t) = \frac{a F}{ES 2\pi\omega_0} \frac{\sin\left(\frac{2\pi\omega_0}{a} x\right)}{\cos\left(\frac{2\pi\omega_0}{a} L\right)} \cos(2\pi\omega_0 t)$$

$$\text{avec } a^2 = \frac{E}{\rho}$$

$$\text{and } N(x, t) = F \frac{\cos\left(\frac{2\pi\omega_0}{a} x\right)}{\cos\left(\frac{2\pi\omega_0}{a} L\right)} \cos(2\pi\omega_0 t)$$

2.1.2.2 Torsion

$$\begin{cases} G I_p \frac{\partial^2 \theta_x}{\partial x^2} - I_{\theta_x} \frac{\partial^2 \theta_x}{\partial t^2} = f(t) \\ u(0) = 0, \quad u(L) = 0 \end{cases}$$

$$G = \frac{E}{2(1+\nu)}$$

$$I_p = \frac{\pi 0,01^4}{2} m^4,$$

$$I_{\theta_x} = \rho I_p$$

$$\theta_x(x, t) = \frac{b F}{G I_p 2\pi\omega_0} \frac{\sin\frac{2\pi\omega_0}{b} x}{\cos\frac{2\pi\omega_0}{b} L} \cos(2\pi\omega_0 t)$$

$$M_T(x, t) = F \frac{\cos\left(\frac{2\pi\omega_0}{b} x\right)}{\cos\left(\frac{2\pi\omega_0}{b} L\right)} \cos(2\pi\omega_0 t)$$

$$\text{avec } b = \frac{G}{\rho}$$

2.2 Results of reference

internal forces (N and MT)

2.3 Uncertainty on the analytical

solution Solution.

2.4 Bibliographical references

- 1) Ratio n° 2314/A of the Institute Aerotechnics "Proposal and realization for new cases tests missing to the validation of beams ASTER"

3 Modelization A

3.1 Characteristic of the modelization

The model is composed of 2 elements straight beam of Timoshenko.

3.2 Characteristics of the mesh

2 elements POU_D_T

3.3 Quantities tested and results

3.3.1 Charges divided into tension

		analytical Results	Results Aster	Variation (%)
normal Force for $x=0$	$t=1/3 s$	4.7247E+02	4.7247E+02	9.12E-07
	$t=2/3 s$	3.92944E+02	3.9294E+02	- 6.08E-07
normal Force for $x=L/2$	$t=1/3 s$	0.0000E+00	2.1985E-12	2.20E-12*
	$t=2/3 s$	0.0000E+00	2.5087E-12	2.51E-12*

* absolute Deviation

3.3.2 concentrated Loading

3.3.2.1 Loading in tension

normal Force for $x=0$

		analytical Results	Results Aster	Variation (%)
	$t=1/3 s$	9.44957E+02	9.44956E+02	- 7.59E-07
	$t=2/3 s$	7.8588E+02	7.8588E+02	3.01E-06

3.3.2.2 Loading in torsion

Twisting moment for $x=0$

		analytical Results	Results Aster	Variation (%)
	$t=1/3 s$	9.4495E+02	9.4495E+02	- 1.88E-06
	$t=2/3 s$	7.8588E+02	7.8589E+02	7.29E-06

4 Summary of the results

This test makes it possible to check that the internal forces of the beam elements in dynamics are correct. The results show a very good agreement with the analytical solution, for a mesh only made up of two elements POU_D_T.